

Silencer[™] Series Brushless DC Motors

Commercial and Industrial

TYPICAL APPLICATIONS

- Medical equipment - pumps, blowers and electric scooters and wheelchairs
- Automatic door and window openers
- Computer-controlled embroidery machines
- Scanners
- Packaging equipment and printing products
- HVAC equipment (air handling)
- Robotic tape storage and retrieval
- Semiconductor handling and insertion machines
- Actuators

FEATURES

- Inside rotor construction for quick acceleration
- 8 pole motor standard, 4 pole motors optional for high speed applications
- Compact size – lengths from 1.3 to 5.5 inches
- Continuous torques from 2.4 to 519 oz-in
- High energy neodymium magnets
- Safe, arcless operation
- High speed capability – up to 20,000 rpm
- High torque per dollar ratio

BENEFITS

- Operation at any single speed - not limited to AC frequency
- Motor life is not limited to brush or commutator life
- An essentially linear speed/torque curve
- Efficient operation without losses associated with brushes and commutation or armature induction
- Precise, variable speed control
- Extremely quiet operation
- Long-life operation

ENCODERS

High resolution, high reliability, and state-of-the-art technology in a small package:

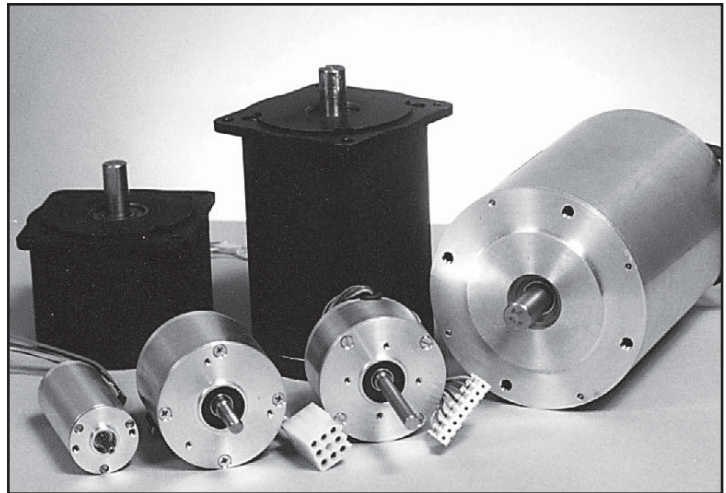
- Bidirectional incremental code
- Up to 1024 cycles standard
- Up to 3 channels: A, B, and index
- TTL / CMOS compatible
- Hewlett Packard HEDS-5500 encoder standard, other configurations and resolutions available

SILENCER BRUSHLESS MOTOR DRIVES

Optimized for use with Silencer Brushless DC motors, these drives provide:

- Multiple operating modes - commutation, velocity, torque, 2 and 4 quadrant
- Feedback using Hall effect sensor or encoder
- Efficient PWM speed control
- CE approved for European applications
- Low cost

BN12, 17, 23, 28, 34 and 42
1.2" to 4.15" Diameter



Quiet, Brushless Motors

Silencer Brushless motors provide smooth, efficient operation and increased speed ranges. Utilizing bonded neo magnets, our BN series motors provide excellent value with their low cost and high torque. Each frame of the BN motors is available in four different lengths with a variety of electrical options to meet a wide range of commercial and industrial operating specifications.

Reliable, Low-cost Operation

The compact BN motors are well-suited for applications demanding low audible noise and long life. An aluminum housing protects the unit in rugged applications and environments. Typical options include electronic drives, encoders and gearheads, as well as Hall effect, resolver and sensorless feedback.

Our engineering department is available for consultation to help you tailor a brushless motor for your specific application.

Note:

- IP65 versions available. Contact factory for information.
- UL Class F Insulation Systems for BN motors available upon request.

NOTES AND TERMS ON BRUSHLESS DC MOTORS

Application Assistance

There are a few typical questions our engineers will ask when discussing your specific application:

- ☐ What torque range is required?
- ☐ What speed range is required?
- ☐ What space is available?
- ☐ What voltage is available?
- ☐ What current is available?
- ☐ Are there any special shaft and / or mounting requirements?

Terms

Back EMF Constant: (Ke) (V / Krpm)

Also referred to as Voltage Constant. This is the voltage generated while the motor is operating which is proportional to speed, but opposing to the applied voltage.

Bearing Life:

The bearing life of an individual ball bearing is the number of revolutions (or hours at a given speed) which the bearing runs before the first evidence of fatigue develops in the material of either ring or of any of the rolling elements.

Bearing Rating Life:

The rating life, L10, of a group of apparently identical ball bearings is the life in millions of revolutions that 90% of the group will complete or exceed. For a single bearing, L10 also refers to the life associated with 90% reliability, L5 refers to 95% reliability and L1 refers to 99% reliability.

Brushless DC Motor:

A brushless DC motor is a motor which is electronically commutated and exhibits the linear speed-torque characteristics of the conventional DC motor. The motors typically use a permanent magnet to produce the rotor field.

Continuous Stall Torque: (Tcs) (oz-in)

The maximum torque at zero speed which a motor can continuously deliver without exceeding its thermal rating.

Encoder:

The encoder is a feedback device which converts mechanical motion into a digital

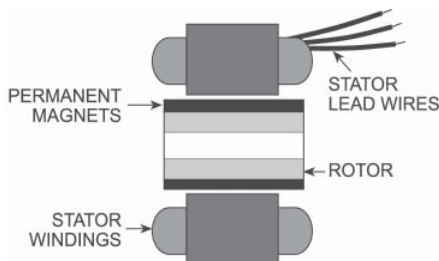
signal. The resolution of the encoder is defined in counts per revolutions as the number of electrical pulses provided in one mechanical revolution. The number of pulses is determined by a metal or glass code wheel and optical sensors.

Hall Effect Sensors:

Hall devices are magnetic sensing devices which produce an electronic signal. This signal provides information to the amplifier to electronically commutate the brushless motor.

Inside Rotor Motor:

This is the most common motor construction. The permanent magnet rotor is on the inside and is surrounded by the wound stator assembly. This is the typical construction of our BN motors.



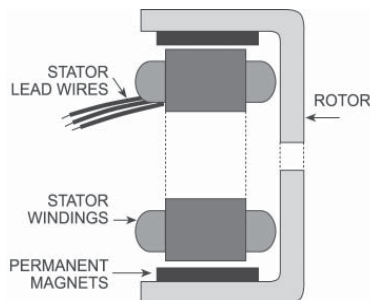
Motor Constant:

(Km) (oz-in / sq rt watts)

The motor constant is the ratio of motor torque to motor input power. It is a figure of merit typically used to compare motor capability.

Outside Rotor Motor:

The outside rotor motor is a special design used in applications where higher rotor inertia is desired. The wound stator field is stationary and located on the inside of the rotating magnetic field. The rotor is typically a magnet inside of a



housing. These motors are our BOH, BOF or BON series.

Peak Torque:

The peak torque of a motor is the maximum amount of torque the motor can produce for short periods of time. In a brushless PMDC motor, the current (and therefore the peak torque) is usually limited by the control electronics.

Permanent Magnet DC Motor:

A permanent magnet DC motor is a motor with a wound armature and a permanent magnetic field. Power is supplied to the armature through brushes and a commutator. This type of motor provides a linear speed / torque performance characteristic. The C-series is our line of PMDC motors in our C-series products.

Resolver:

The resolver is an electromechanical device which converts shaft position into analog signals. The resolver output is a sine and a cosine signal. There are several types of resolvers. The brushless motor typically uses the single speed transmitter type resolver. Position is determined by the ratio of the sine output amplitude to the cosine output amplitude. A single speed resolver produces one sine and cosine wave at the output for each mechanical revolution. We manufacture both single speed and multispeed resolvers.

Torque Sensitivity: (Kt) (oz-in / Amp)

The relationship of the output torque to the input current of the motor.

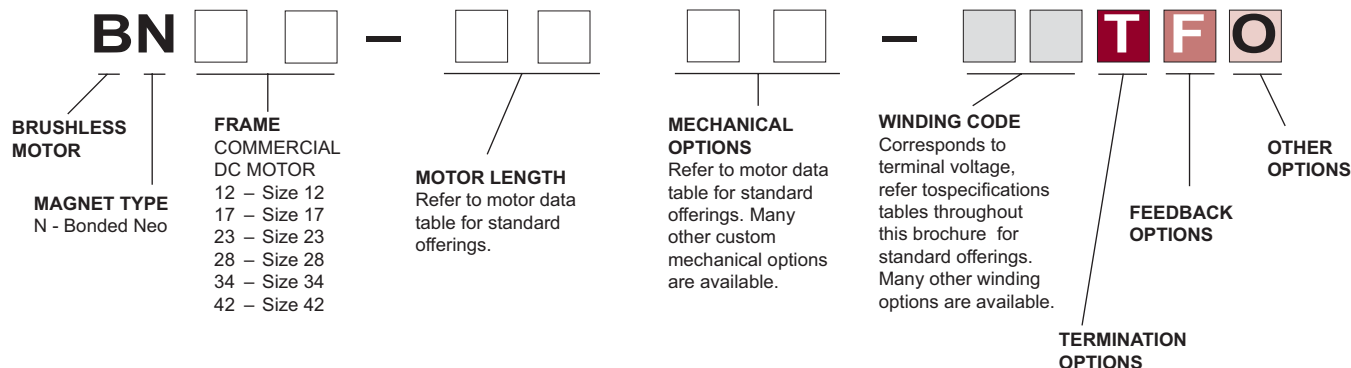
Terminal Resistance: (Rt) (ohms)

This is the line to line resistance at 25°C. The value of resistance in the motor is determined by the temperature of the windings in a particular application.

Brushless Motors

SPECIFICATION AND NUMBERING SYSTEM

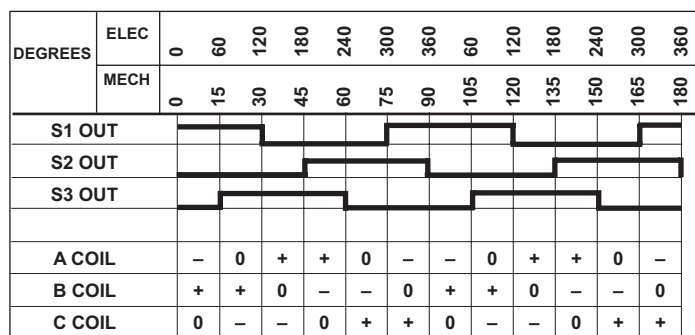
Part Numbering System Guide



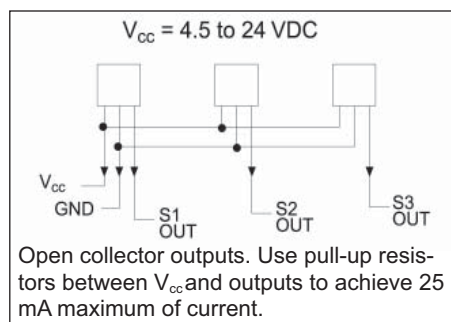
Conversion Table

FROM	TO	MULTIPLY BY
Length		
inches	cm	2.540
feet	cm	30.48
cm	inches	.3937
cm	feet	3.281 x 10 ⁻²
Mass		
oz	g	28.35
lb	g	453.6
g	oz	3.527 x 10 ⁻²
lb	oz	16.0
g	lb	2.205 x 10 ⁻³
oz	lb	6.250 x 10 ⁻²
Torque		
oz-in	g-cm	72.01
lb-ft	g-cm	1.383 x 10 ⁴
g-cm	oz-in	1.389 x 10 ⁻²
lb-ft	oz-in	192.0
g-cm	lb-ft	7.233 x 10 ⁻⁵
oz-in	lb-ft	5.208 x 10 ⁻³
Rotation		
rpm	degrees/sec	6.0
rad/sec	degrees/sec	57.30
degrees/sec	rpm	.1667
rad/sec	rpm	9.549
degrees/sec	rad/sec	1.745 x 10 ⁻²
rpm	rad/sec	.1047
Moment Of Inertia		
oz-in ²	g-cm ²	182.9
lb-ft ²	g-cm ²	4.214 x 10 ⁵
g-cm ²	oz-in ²	5.467 x 10 ⁻³
lb-ft ²	oz-in ²	2.304 x 10 ³
g-cm ²	lb-ft ²	2.373 x 10 ⁻⁶
oz-in ²	lb-ft ²	4.340 x 10 ⁻⁴
oz-in-sec ²	g-cm ²	7.062 x 10 ⁴

Timing Diagram for Hall Switches



Hall Effect Switches



IMPORTANT

The operational life and performance of any motor is dependent upon individual operating parameters, environment, temperature and other factors. Your specific application results may vary. Please consult the factory to discuss your requirements.

Bearing Load Rating (lbs)

Motor Size	Dynamic	Static
BN-12	295	110
BN-17	331	134
BN-23	743	304
BN-28	1022	422
BN-34	1532	683
BN-42	1340	725

BN12 SPECIFICATIONS -

Continuous Stall Torque 2.4 - 8.6 oz-in (0.0170 - 0.0607 Nm)
Peak Torque 13 - 77 oz-in (0.0918 - 0.5437 Nm)

Part Number*		BN12-13AF-    			BN12-18AF-    			BN12-23AF-    			BN12-28AF-    		
Winding Code**		01	02	03	01	02	03	01	02	03	01	02	03
L = Length	inches	1.30			1.80*			2.30			2.80		
	millimeters	33.02			45.72			58.42			71.12		
Terminal Voltage	volts DC	12.0	24.0	36.0	12.0	24.0	36.0	12.0	24.0	36.0	12.0	24.0	36.0
Peak Torque	oz-in	13.0	13.0	14.0	37.0	37.0	39.0	58.0	58.0	61.0	77.0	77.0	72.0
	Nm	0.0918	0.0918	0.0989	0.2613	0.2613	0.2754	0.4096	0.4096	0.4308	0.5437	0.5437	0.5084
Continuous Stall Torque	oz-in	2.4	2.4	2.4	4.9	5.0	5.0	6.9	6.9	6.9	8.3	8.6	8.6
	Nm	0.0169	0.0169	0.0169	0.0346	0.0353	0.0353	0.0487	0.0487	0.0487	0.0586	0.0607	0.0607
Rated Speed	RPM	13027.0	12736.0	13753.0	11928.0	11448.0	12320.0	10604.0	10601.0	11489.0	11036.0	10253.0	9529.0
	rad/sec	1364	1334	1440	1249	1199	1290	1110	1110	1203	1156	1074	998
Rated Torque	oz-in	1.8	1.8	1.8	3.5	3.6	3.5	5.0	5.0	4.7	5.4	5.9	6.2
	Nm	0.0127	0.0127	0.0127	0.0247	0.0254	0.0247	0.0353	0.0353	0.0332	0.0381	0.0417	0.0438
Rated Current	Amps	2.26	1.13	0.77	3.49	1.76	1.20	4.32	2.16	1.46	4.81	2.46	1.61
Rated Power	watts	17.3	17.0	18.3	30.9	30.5	31.9	39.2	39.2	39.9	44.1	44.7	43.7
Torque Sensitivity	oz-in/amp	1.02	2.06	2.95	1.24	2.56	3.64	1.42	2.84	4.01	1.41	2.99	4.75
	Nm/amp	0.0072	0.0145	0.0208	0.0088	0.0181	0.0257	0.0100	0.0201	0.0283	0.0100	0.0211	0.0335
Back EMF	volts/KRPM	0.75	1.53	2.18	0.92	1.89	2.69	1.05	2.10	2.96	1.04	2.21	3.51
	volts/rad/sec	0.0072	0.0145	0.0208	0.0088	0.0181	0.0257	0.0100	0.0201	0.0283	0.0100	0.0211	0.0335
Terminal Resistance	ohms	0.953	3.89	7.85	0.403	1.67	3.36	0.294	1.18	2.36	0.219	0.934	2.36
Terminal Inductance	mH	0.254	1.100	2.210	0.181	0.742	1.460	0.172	0.692	1.374	0.128	0.447	1.220
Motor Constant	oz-in/sq.rt.watt	1.04	1.04	1.05	1.95	1.98	1.99	2.62	2.61	2.61	3.01	3.09	3.09
	Nm/sq.rt.watt	0.00738	0.00738	0.00744	0.01379	0.01399	0.01402	0.01849	0.01846	0.01843	0.02128	0.02185	0.02183
Rotor Inertia	oz-in-sec ² x10 ⁻³	0.040	0.040	0.040	0.080	0.080	0.080	0.120	0.120	0.120	0.16	0.16	0.16
	g-cm ²	2.82	2.82	2.82	5.65	5.65	5.65	8.47	8.47	8.47	11.3	11.3	11.3
Weight	oz	3.6	3.6	3.6	5.5	5.5	5.5	7.3	7.3	7.3	9.1	9.2	9.2
	g	102.2	102.2	102.2	156.2	156.2	156.2	207.3	207.3	207.3	258.4	261.3	261.3
# of Poles		8.0	8.0	8.0	8.0	8.0	8.0	8.0	8.0	8.0	8.0	8.0	8.0
Timing		120°	120°	120°	120°	120°	120°	120°	120°	120°	120°	120°	120°
Mech. Time Constant	ms	5.2	5.2	5.1	3.0	2.9	2.9	2.5	2.5	2.5	2.5	2.4	2.4
Electrical Time Constant	ms	0.14	0.14	0.14	0.24	0.25	0.25	0.29	0.29	0.29	0.29	0.31	0.31
Thermal Resistivity	deg. C/watt	10.7	10.3	11.2	9.5	8.9	9.3	8.3	8.3	8.3	7.7	7.3	7.4
Speed/Torque Gradient	rpm/oz-in	1245.8	1234.2	1220.6	353.3	345.2	343.2	197.2	197.9	198.8	149.3	141.3	141.6

Notes:

- Motor mounted to a 4" x 4" x 1/4" aluminum plate, still air.
- Maximum winding temperature of 155°C.
- Typical electrical specifications at 25°C.
- Motor Terminal Voltages are representative only; motors may be operated at voltages other than those listed in the table. For assistance please contact our applications engineer.

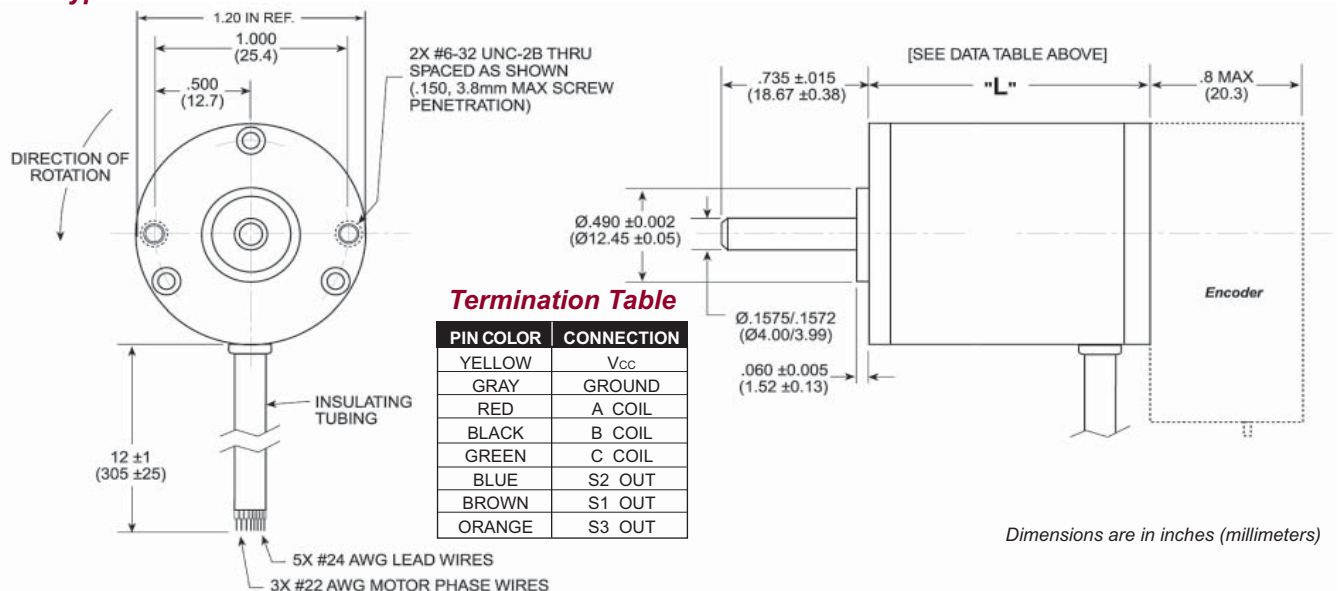
*Many other custom mechanical options are available – consult factory.

**Many other winding options are available – consult factory.

Select your options below and place their code in its corresponding block as shown on page 8.

 TERMINATION	 FEEDBACK OPTIONS	 OTHER OPTIONS
L – Leads (std)	H – Hall Effect (std)	D – Drive
C – Connector	R – Resolver	E – Encoder
M – MS connector	S – Sensorless	G – Gearhead

BN12 Typical Outline



BN12 EU SPECIFICATIONS - *Continuous Stall Torque 2.4 - 8.6 oz-in (0.0170 - 0.0587 Nm)*
Peak Torque 13 - 77 oz-in (0.0918 - 0.544 Nm)

Notes:

1. Motor mounted to a 4" x 4" x 1/4" aluminum plate, still air.
2. Maximum winding temperature of 155°C.
3. Typical electrical specifications at 25°C.
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*Many other custom mechanical options are available – consult factory.

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Select your options below and place their code in its corresponding block as shown on page 8.

L – Leads (std)
C – Connector
M – MS connector

H – Hall Effect (std)
R – Resolver
S – Sensorless

D – Drive
E – Encoder
G – Gearhead

Termination Table

3X M2.5 LOCATED 120° APART ON 30.48 (1.19) 3.81 MAX SCREW PENETRATION

Ø 30.48 ± 0.25

DIRECTION OF ROTATION

1.52

"L"

Ø 13

12 ± 0.38

Ø 4

13.97

304.8 ± 25.4

2X M2.5 X 2.08 DEEP ON Ø 19.05 BC

INSULATING TUBING

3X ± 22 AWG MOTOR PHASE WIRES
5X ± 24 AWG LEAD WIRES

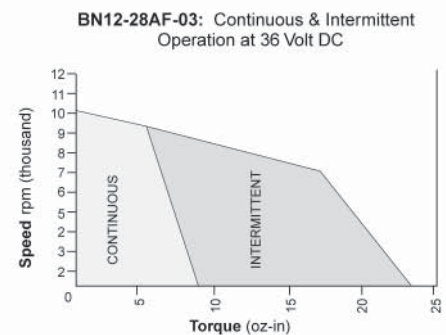
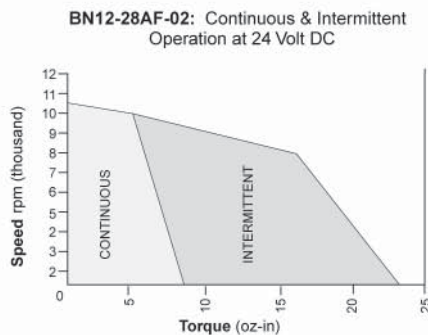
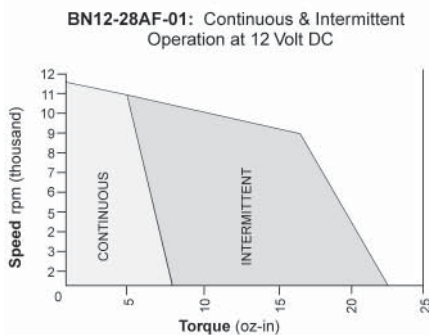
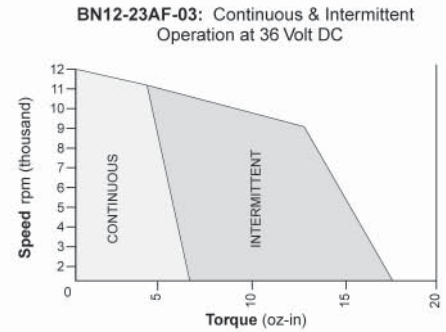
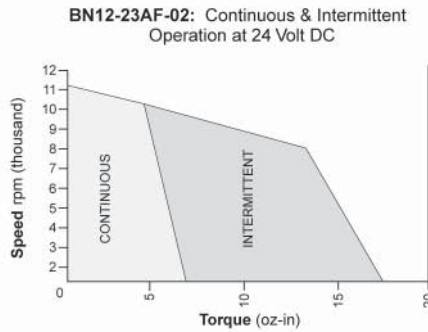
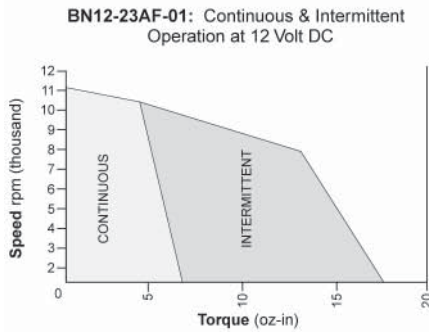
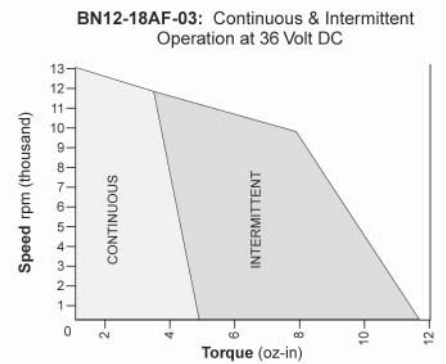
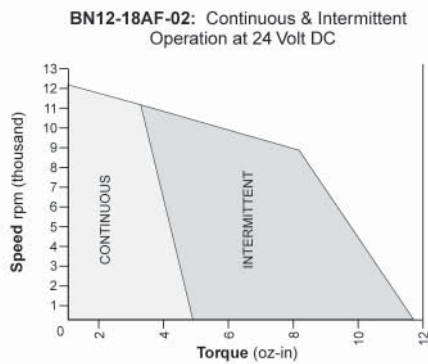
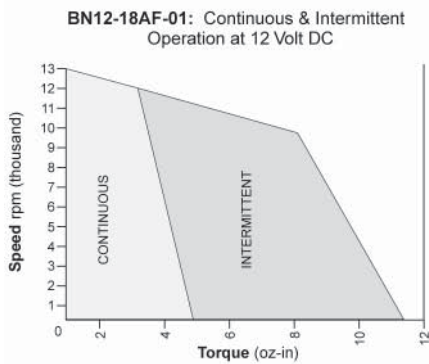
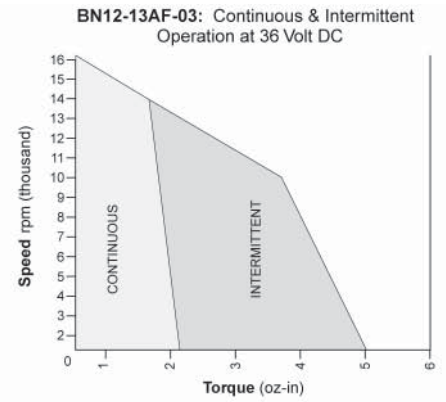
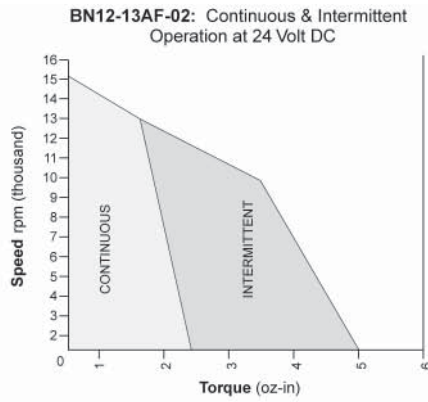
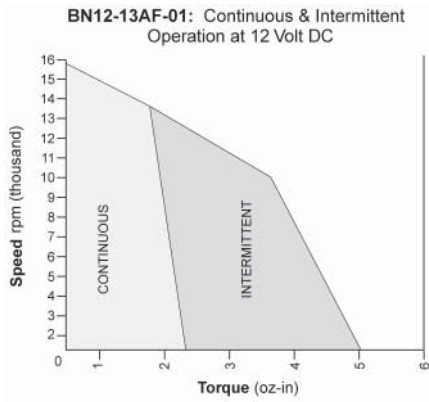
THIS SURFACE TO BE MARKED OR LABELED AS FOLLOWS:
UNIT TYPE
DATE CODE

4

PIN COLOR	CONNECTION
YELLOW	V _{CC}
GRAY	GROUND
RED	A COIL
BLACK	B COIL
GREEN	C COIL
BLUE	S2 OUT
BROWN	S1 OUT
ORANGE	S3 OUT

Dimensions are in inches (millimeters)

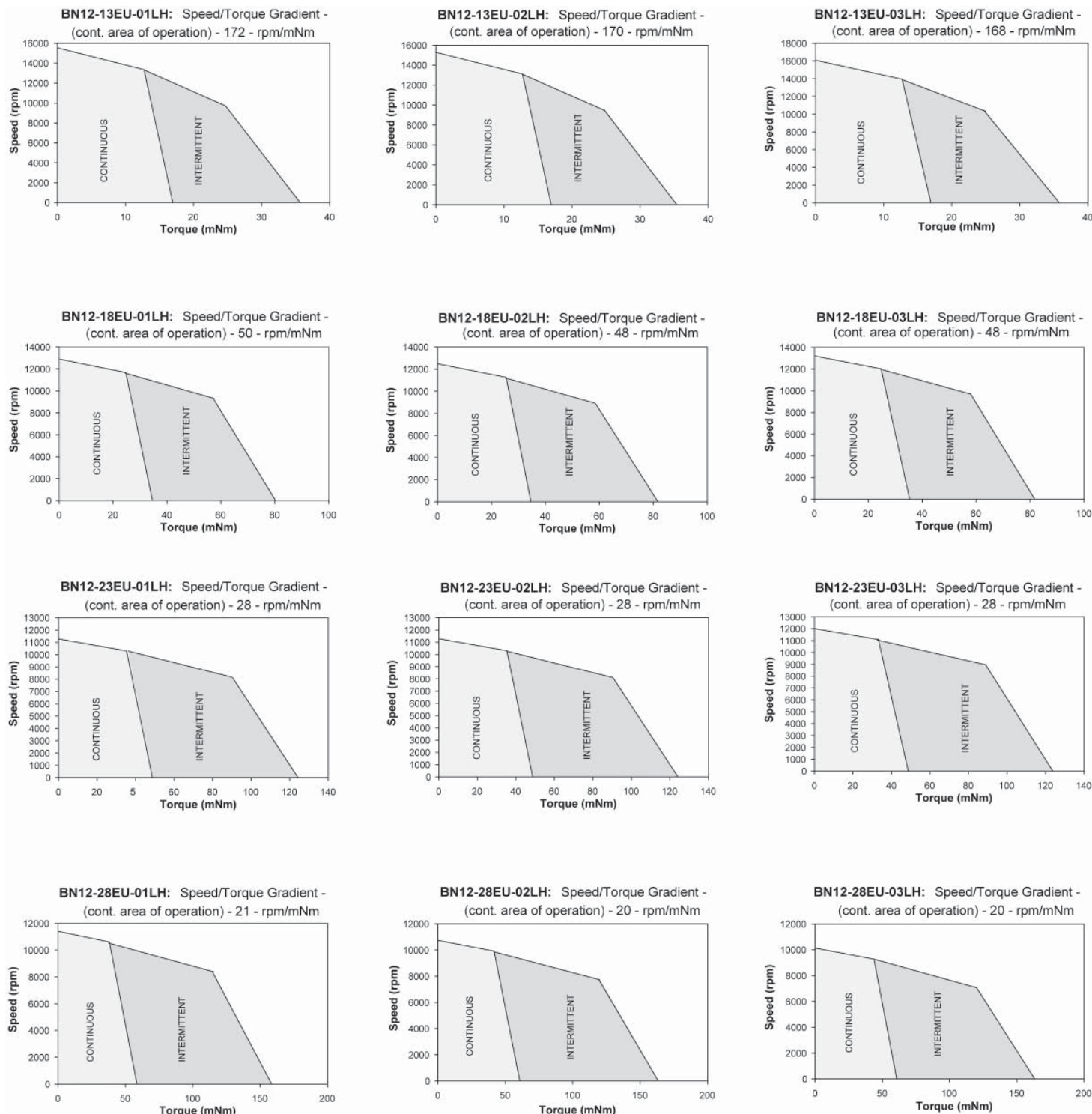
BN12 Performance Curves



Note: Intermittent operation is based on a 20% duty cycle of one minute on, four minutes off.
Please contact the factory regarding the duty cycle of your application.

Brushless Motors

BN12 EU Performance Curves



Note: Intermittent operation is based on a 20% duty cycle of one minute on, four minutes off.
Please contact the factory regarding the duty cycle of your application.

BN17 SPECIFICATIONS - Continuous Stall Torque 7.0 to 16.0 oz-in (0.049 - 0.113 Nm) Peak Torque 64 - 149 oz-in (0.45 - 1.05 Nm)

Part Number*		BN17-15AA- ☐ ☐ ☐ ☐ ☐			BN17-20AA- ☐ ☐ ☐ ☐ ☐			BN17-25AA- ☐ ☐ ☐ ☐ ☐		
Winding Code**		01	02	03	01	02	03	01	02	03
L = Length	inches	1.50			2.00			2.50		
	millimeters	38.1			50.8			63.5		
Terminal Voltage	volts DC	12.0	24.0	36.0	12.0	24.0	36.0	12.0	24.0	36.0
Peak Torque	oz-in	64.0	83.0	88.00	116.0	116.0	124.0	140.0	149.0	142.0
	Nm	0.4519	0.5861	0.6214	0.8191	0.8191	0.8756	0.9886	1.0522	1.0027
Continuous Stall Torque	oz-in	7.0	7.0	8.0	12.0	12.0	12.0	15.0	15.0	16.0
	Nm	0.0494	0.0494	0.0565	0.0847	0.0847	0.0847	0.1059	0.1059	0.1130
Rated Speed	RPM	10623.0	15627.0	14644.0	8659.0	9172.0	9771.0	8414.0	8452.0	7834.0
	rad/sec	1112	1636	1534	907	960	1023	881	885	820
Rated Torque	oz-in	6.7	5.4	6.3	9.5	8.7	8.5	10.7	11.0	11.5
	Nm	0.0473	0.0381	0.0445	0.0671	0.0614	0.0600	0.0756	0.0777	0.0812
Rated Current	Amps	5.65	3.27	2.38	6.29	3.05	2.10	6.90	3.54	2.30
Rated Power	watts	52.2	62.4	68.8	60.8	59.0	61.4	66.6	68.7	66.6
Torque Sensitivity	oz-in/amp	1.28	1.86	2.95	1.64	3.13	4.45	1.70	3.40	5.44
	Nm/amp	0.0090	0.0131	0.0208	0.0116	0.0221	0.0314	0.0120	0.0240	0.0384
Back EMF	volts/KRPM	0.95	1.38	2.18	1.21	2.31	3.29	1.26	2.51	4.02
	volts/rad/sec	0.0090	0.0131	0.0208	0.0116	0.0221	0.0314	0.0120	0.0240	0.0384
Terminal Resistance	ohms	0.24	0.54	1.20	0.17	0.65	1.30	0.15	0.55	1.38
Terminal Inductance	mH	0.23	0.48	1.22	0.17	0.69	1.40	0.15	0.61	1.57
Motor Constant	oz-in/sq.rt.watts	2.69	2.56	2.71	4.13	3.92	3.93	4.67	4.64	4.65
	Nm/sq.rt.watts	0.01900	0.01808	0.01914	0.02916	0.02768	0.02775	0.03298	0.03277	0.03284
Rotor Inertia	oz-in-sec ² x10 ⁻³	0.23	0.23	0.23	0.39	0.39	0.39	0.54	0.54	0.54
	g-cm ²	16.2	16.2	16.2	27.5	27.5	27.5	38.1	38.1	38.1
Weight	oz	6.7	6.7	6.7	10.5	10.5	10.5	13.4	13.4	13.4
	g	190	190	190	298	298	298	380	380	380
# of Poles		4.0	4.0	4.0	4.0	4.0	4.0	4.0	4.0	4.0
Timing		120°	120°	120°	120°	120°	120°	120°	120°	120°
Mech. Time Constant	ms	4.8	5.1	4.5	3.5	3.7	3.6	4.0	3.6	3.6
Electrical Time Constant	ms	0.96	0.89	1.02	1.00	1.06	1.08	1.00	1.11	1.14
Thermal Resistivity	deg. C/watt	8.2	8.3	8.1	6.9	6.9	6.9	6.0	6.0	6.0
Speed/Torque Gradient	rpm/oz-in.	197.4	210.4	186.6	85.7	89.9	88.8	70.0	64.4	63.1

Notes:

- Motor mounted to a 4" x 4" x 1/4" aluminum plate, still air.
 - Maximum winding temperature of 155°C.
 - Typical electrical specifications at 25°C.
 - Calculated (theoretical) speed/torque gradient.
 - Shaft options for encoder mounting available.
- * Many other custom mechanical options are available – consult factory.
** Many other winding options are available – consult factory.

*Many other custom mechanical options are available – consult factory.

**Many other winding options are available – consult factory.

Select your options below and place their code in its corresponding block as shown on page 8.

T TERMINATION

- L – Leads (std)
C – Connector
M – MS connector

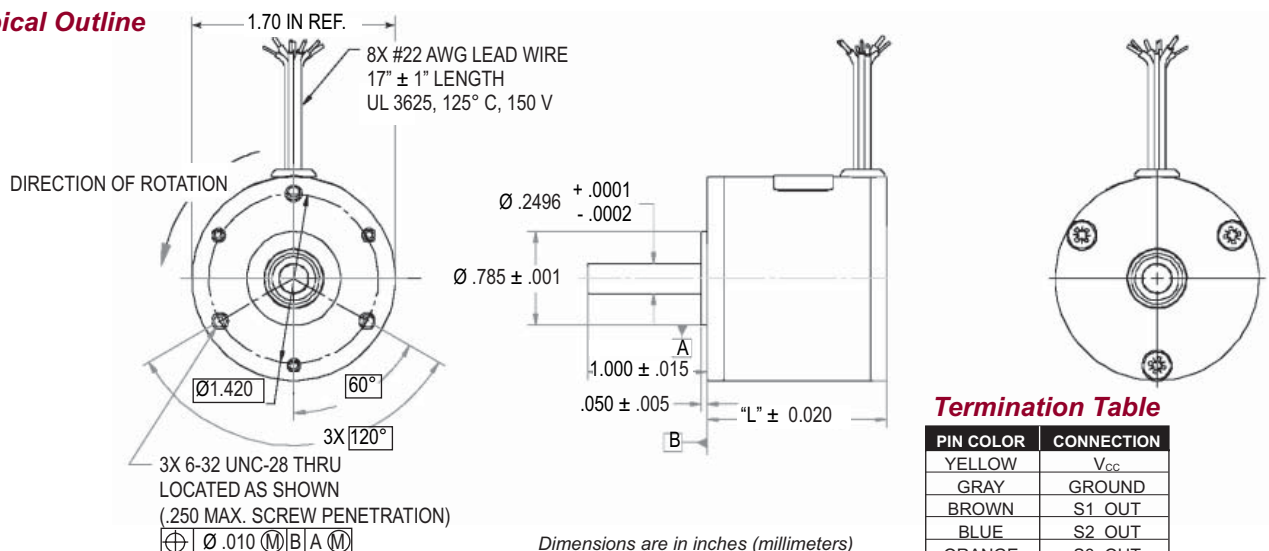
F FEEDBACK OPTIONS

- H – Hall Effect (std)
R – Resolver
S – Sensorless

O OTHER OPTIONS

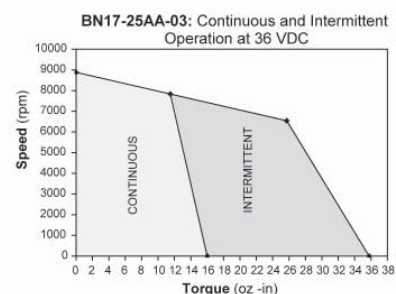
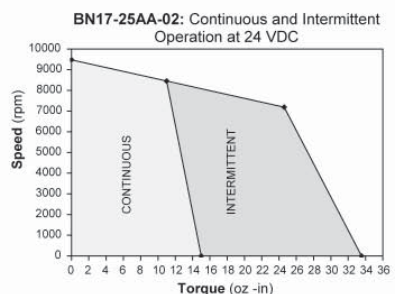
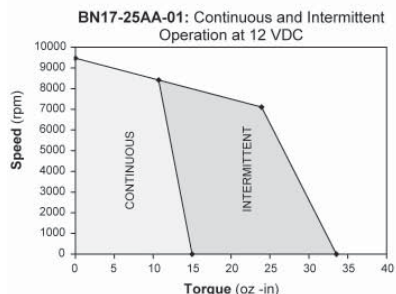
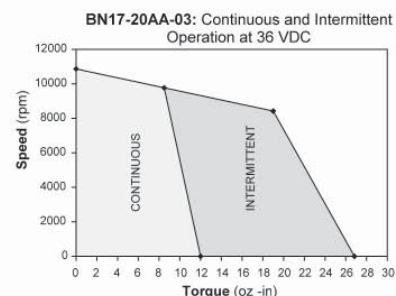
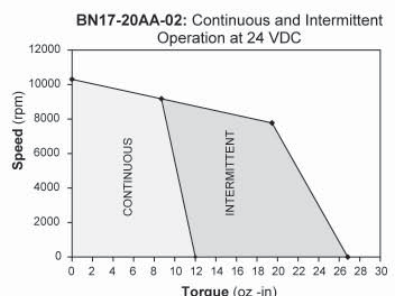
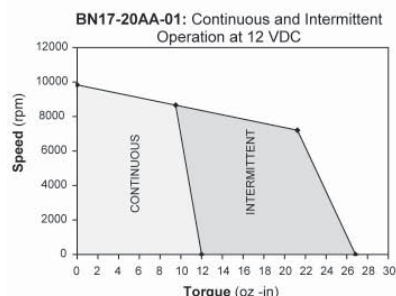
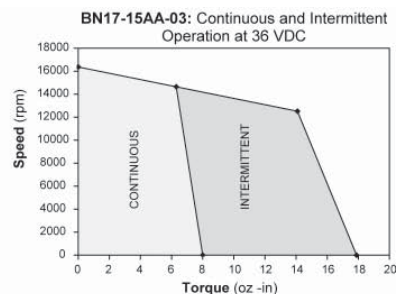
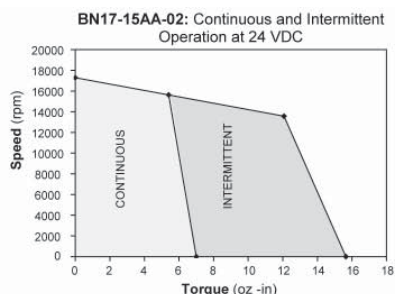
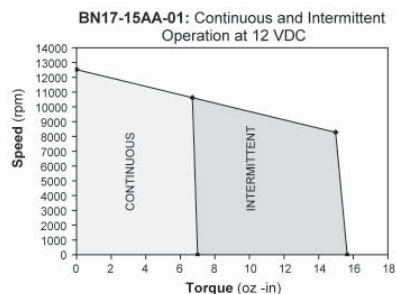
- D – Drive
E – Encoder
G – Gearhead

BN17 Typical Outline



Brushless Motors

BN17 Performance Curves



Note: Intermittent operation is based on a 20% duty cycle of one minute on, four minutes off.
Please contact the factory regarding the duty cycle of your application.

Timing Diagram (4 Pole) CCW Rotation

DEGREES	ELEC	0	60	120	180	240	300	360	60	120	180	240	300	360
	MECH	0	30	60	90	120	150	180	210	240	270	300	330	360
S1 OUT														
S2 OUT														
S3 OUT														
A COIL		-	0	+	+	0	-	-	0	+	+	0	-	
B COIL		+	+	0	-	-	0	+	+	0	-	-	0	
C COIL		0	-	-	0	+	+	0	-	-	0	+	+	

BN23 SPECIFICATIONS -

Continuous Stall Torque 12.6 - 41 oz-in (0.0890 - 0.290 Nm)
Peak Torque 35 - 186 oz-in (0.248 - 1.32 Nm)

Part Number*		BN23-13PM-			BN23-18PM-			BN23-23PM-			BN23-28PM-		
Winding Code**		01	02	03	01	02	03	01	02	03	01	02	03
L = Length	inches	1.41			1.91			2.41			2.91		
	millimeters	35.8			48.5			61.2			73.9		
Terminal Voltage	volts DC	24.0	36.0	48.0	24.0	36.0	48.0	24.0	36.0	48.0	24.0	36.0	48.0
Peak Torque	oz-in	35.0	35.0	35.0	88.0	88.0	88.0	143.0	143.0	143.0	186.0	186.0	186.0
	Nm	0.2472	0.2472	0.2472	0.6214	0.6214	0.6214	1.0098	1.0098	1.0098	1.3134	1.3134	1.3134
Continuous Stall Torque	oz-in	12.6	12.6	12.6	24.2	24.2	24.2	34.5	34.5	34.5	41.0	41.0	41.0
	Nm	0.0890	0.0890	0.0890	0.1709	0.1709	0.1709	0.2436	0.2436	0.2436	0.2895	0.2895	0.2895
Rated Speed	RPM	12235.0	13040.0	12060.0	9810.0	10185.0	10985.0	8585.0	9490.0	8587.0	7640.0	8090.0	8720.0
	rad/sec	1281	1366	1263	1027	1067	1150	899	994	899	800	847	913
Rated Torque	oz-in	8.7	8.2	8.8	16.6	16.3	14.9	23.9	21.2	23.9	28.5	27.2	24.9
	Nm	0.0614	0.0579	0.0621	0.1172	0.1151	0.1052	0.1688	0.1497	0.1688	0.2013	0.1921	0.1758
Rated Current	Amps	4.10	2.75	2.10	6.00	4.10	3.00	7.40	4.90	3.70	8.00	5.40	4.00
Rated Power	watts	78.3	79.1	79.1	120.8	123.1	120.8	152.2	148.5	151.4	161.1	163.4	160.4
Torque Sensitivity	oz-in/amp	2.58	3.67	5.22	3.31	4.81	6.02	3.82	5.25	7.63	4.26	6.08	7.61
	Nm/amp	0.0182	0.0259	0.0369	0.0234	0.0340	0.0425	0.0270	0.0371	0.0539	0.0301	0.0429	0.0537
Back EMF	volts/KRPM	1.91	2.72	3.86	2.45	3.56	4.45	2.82	3.88	5.65	3.15	4.50	5.62
	volts/rad/sec	0.0182	0.0259	0.0369	0.0234	0.0340	0.0425	0.0270	0.0371	0.0539	0.0301	0.0429	0.0537
Terminal Resistance	ohms	0.465	0.939	1.89	0.246	0.507	0.800	0.178	0.347	0.715	0.181	0.366	0.576
Terminal Inductance	mH	0.374	0.758	1.53	0.251	0.531	0.829	0.217	0.410	0.867	0.242	0.493	0.770
Motor Constant	oz-in/sq.rt.watt	3.78	3.79	3.80	6.67	6.76	6.73	9.05	8.91	9.02	10.01	10.05	10.03
	Nm/sq.rt.watt	0.02672	0.02674	0.02681	0.04713	0.04770	0.04753	0.06394	0.06294	0.06372	0.07071	0.07097	0.07081
Rotor Inertia	oz-in-sec ² x10 ⁻³	0.51	0.51	0.51	0.99	0.99	0.99	1.50	1.50	1.50	1.90	1.90	1.90
	g-cm ²	36.0	36.0	36.0	69.9	69.9	69.9	105.9	105.9	105.9	134.1	134.1	134.1
Weight	oz	10.0	10.0	10.0	15.0	15.0	15.0	21.0	21.0	21.0	26.0	26.0	26.0
	g	284.0	284.0	284.0	426.0	426.0	426.0	596.4	596.4	596.4	738.4	738.4	738.4
# of Poles		8.0	8.0	8.0	8.0	8.0	8.0	8.0	8.0	8.0	8.0	8.0	8.0
Timing		120°	120°	120°	120°	120°	120°	120°	120°	120°	120°	120°	120°
Mech. Time Constant	ms	5.0	5.0	5.0	3.1	3.1	3.1	2.6	2.7	2.6	2.7	2.7	2.7
Electrical Time Constant	ms	0.80	0.81	0.81	1.02	1.05	1.04	1.22	1.18	1.21	1.34	1.35	1.34
Thermal Resistivity	deg. C/watt	5.3	5.3	4.7	4.5	4.2	4.6	4.1	3.8	4.1	3.4	3.3	3.3
Speed/Torque Gradient	rpm/oz-in	94.4	94.1	93.8	30.3	29.6	29.9	16.5	17.0	16.6	13.5	13.4	13.5

Notes:

- Motor mounted to a 6" x 6" x 1/4" aluminum plate, still air.
- Maximum winding temperature of 155°C.
- Typical electrical specifications at 25°C.
- Data shown for 8 pole motors. Please consult factory for 4 pole specifications.
- Motor Terminal Voltages are representative only; motors may be operated at voltages other than those listed in the table. For assistance please contact our applications engineer.

*Many other custom mechanical options are available – consult factory.

**Many other winding options are available – consult factory.

Select your options below and place their code in its corresponding block as shown on page 8.

T TERMINATION

L – Leads (std)
C – Connector
M – MS connector

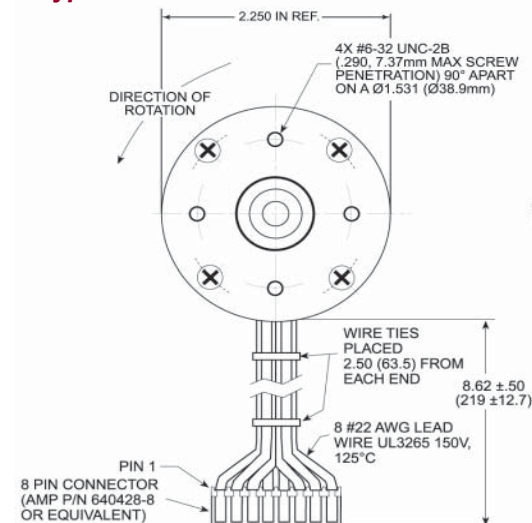
F FEEDBACK OPTIONS

H – Hall Effect (std)
R – Resolver
S – Sensorless

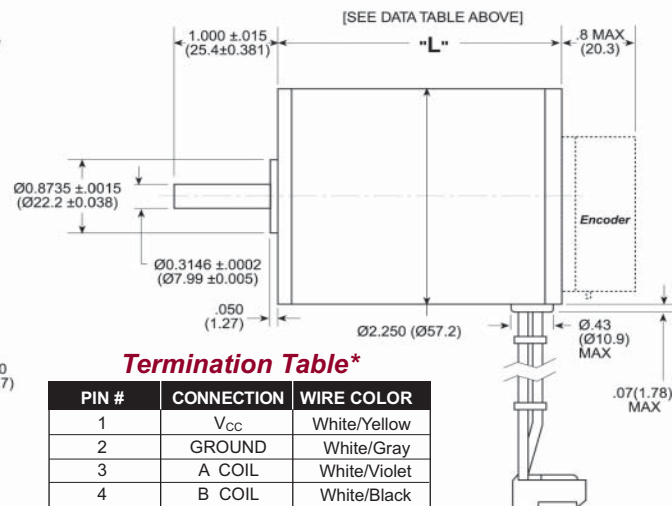
O OTHER OPTIONS

D – Drive
E – Encoder
G – Gearhead

BN23 Typical Outline



*We reserve the right to use solid color wires or white wires with color trace.



Termination Table*

PIN #	CONNECTION	WIRE COLOR
1	V _{CC}	White/Yellow
2	GROUND	White/Gray
3	A COIL	White/Violet
4	B COIL	White/Black
5	C COIL	Green
6	S2 OUT	White/Blue
7	S1 OUT	White/Brown
8	S3 OUT	White

Dimensions are in inches (millimeters)

Brushless Motors

BN23 EU SPECIFICATIONS -

Continuous Stall Torque 12.6 - 41 oz-in (0.0890 - 0.290 Nm)
Peak Torque 35 - 186 oz-in (0.248 - 1.32 Nm)

Part Number*		BN23-13EU-   			BN23-18EU-   			BN23-23EU-   			BN23-28EU-   		
Winding Code**		01	02	03	01	02	03	01	02	03	01	02	03
L = Length	inches	1.41			1.91			2.41			2.91		
	millimeters	35.8			48.5			61.2			73.9		
Terminal Voltage	volts DC	24	36	48	24	36	48	24	36	48	24	36	48
Peak Torque	oz-in	35	35	35	88	88	88	143	143	143	186	186	186
	Nm	0.248	0.248	0.248	0.622	0.622	0.622	1.01	1.01	1.01	1.32	1.32	1.32
Continuous Stall Torque	oz-in	12.6	12.6	12.6	24.2	24.2	24.2	34.5	34.5	34.5	41.0	41.0	41.0
	Nm	0.0890	0.0890	0.0890	0.171	0.171	0.171	0.244	0.244	0.244	0.290	0.290	0.290
Rated Speed	RPM	12235	13040	12060	9810	10185	10985	8585	9490	8587	7640	8090	8720
	rad/sec	1281	1366	1263	1028	1067	1151	899	994	899	800	848	914
Rated Torque	oz-in	8.70	8.20	8.80	16.6	16.3	14.9	23.9	21.2	23.9	28.5	27.2	24.9
	Nm	0.0615	0.0579	0.0622	0.118	0.116	0.106	0.169	0.150	0.169	0.202	0.192	0.176
Rated Current	Amps	4.10	2.75	2.10	6.00	4.10	3.0	7.40	4.90	3.70	8.00	5.40	4.00
Rated Power	watts	78.3	79.1	79.1	120.8	123.1	120.8	152.2	148.5	151.4	161.1	163.4	160.4
Torque Sensitivity	oz-in/amp	2.58	3.67	5.22	3.31	4.81	6.02	3.82	5.25	7.63	4.26	6.08	7.61
	Nm/amp	0.0183	0.0260	0.0369	0.0234	0.0340	0.0425	0.0270	0.0371	0.0540	0.0301	0.0430	0.0537
Back EMF	volts/KRPM	1.91	2.72	3.86	2.45	3.56	4.45	2.82	3.88	5.65	3.15	4.50	5.62
	volts/rad/sec	0.0183	0.0260	0.0369	0.0234	0.0340	0.0425	0.0270	0.0371	0.0540	0.0301	0.0430	0.0537
Terminal Resistance	ohms	0.465	0.939	1.89	0.246	0.507	0.800	0.178	0.347	0.715	0.181	0.366	0.576
Terminal Inductance	mH	0.374	0.758	1.53	0.251	0.531	0.829	0.217	0.410	0.867	0.242	0.493	0.770
Motor Constant	oz-in/sq.rt.watt	3.8	3.8	3.8	6.7	6.7	6.7	9.0	9.0	9.0	10.0	10.0	10.0
	Nm/sq.rt.watt	0.0269	0.0269	0.0269	0.0474	0.0474	0.0474	0.0636	0.0636	0.0636	0.0707	0.0707	0.0707
Rotor Inertia	oz-in-sec ²	.51E-03	.51E-03	.51E-03	.99E-03	.99E-03	.99E-03	1.5E-03	1.5E-03	1.5E-03	1.9E-03	1.9E-03	1.9E-03
	g-cm ²	36.1	36.1	36.1	69.9	69.9	69.9	106	106	106	135	135	135
Weight	oz	10.0	10.0	10.0	15.0	15.0	15.0	21.0	21.0	21.0	26.0	26.0	26.0
	g	284	284	284	426	426	426	596	596	596	738	738	738

Notes:

- Motor mounted to a 6" x 6" x 1/4" aluminum plate, still air.
- Maximum winding temperature of 155°C.
- Typical electrical specifications at 25°C.
- Data shown for 8 pole motors. Please consult factory for 4 pole specifications.
- Motor Terminal Voltages are representative only; motors may be operated at voltages other than those listed in the table. For assistance please contact our applications engineer.

*Many other custom mechanical options are available – consult factory.

**Many other winding options are available – consult factory.

Select your options below and place their code in its corresponding block as shown on page 8.

T TERMINATION

- L – Leads
- C – Connector (std)
- M – MS connector

F FEEDBACK OPTIONS

- H – Hall Effect (std)
- R – Resolver
- S – Sensorless

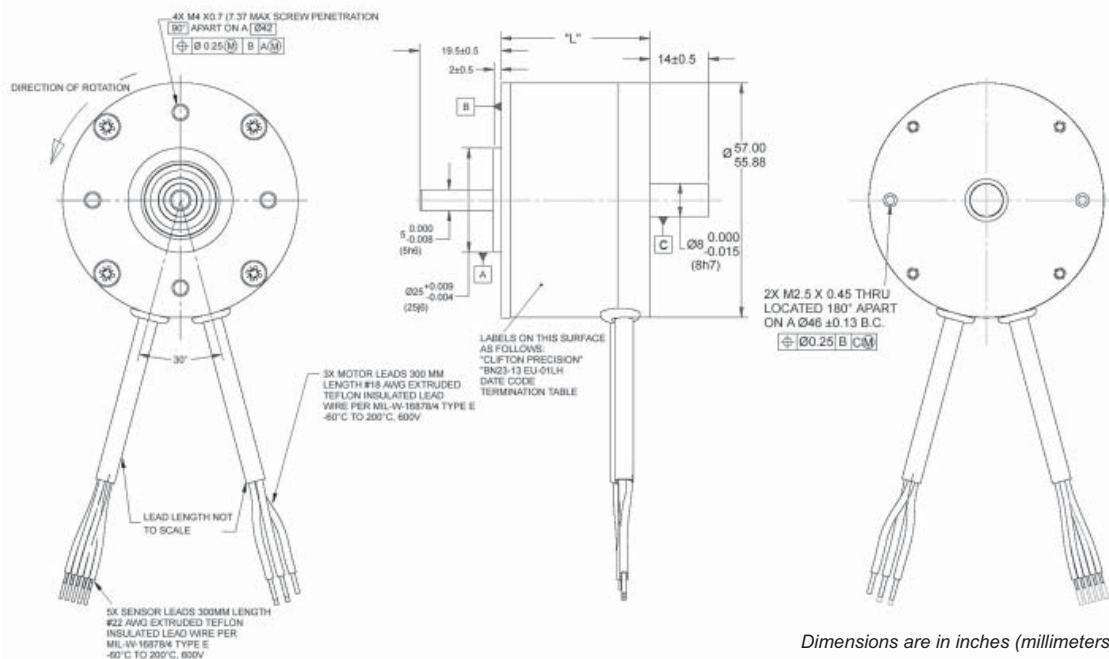
O OTHER OPTIONS

- D – Drive
- E – Encoder
- G – Gearhead

BN23 EU Typical Outline

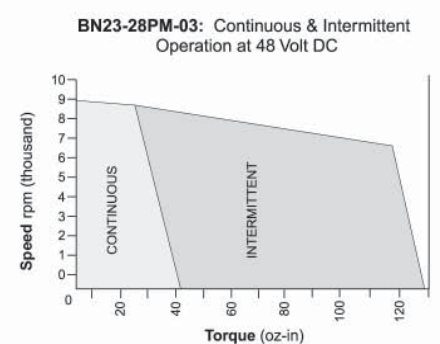
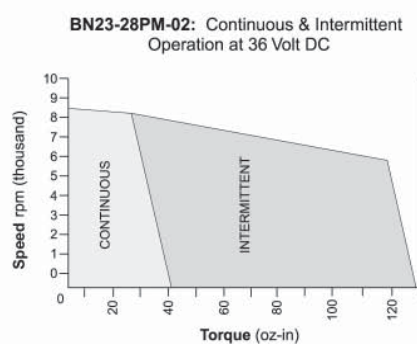
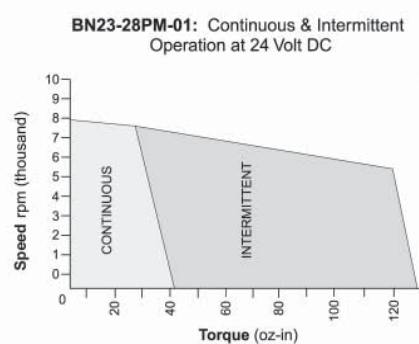
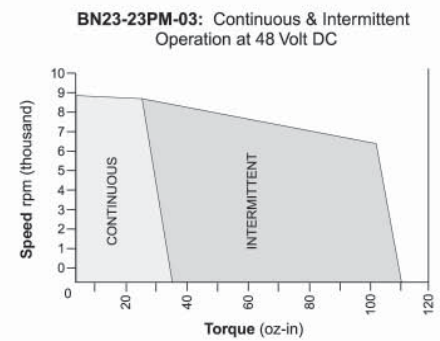
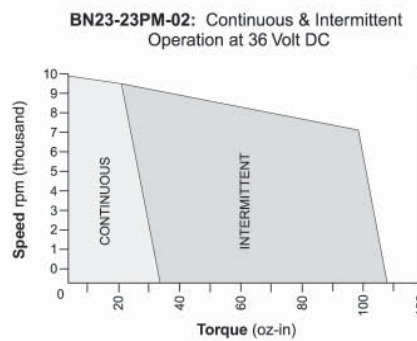
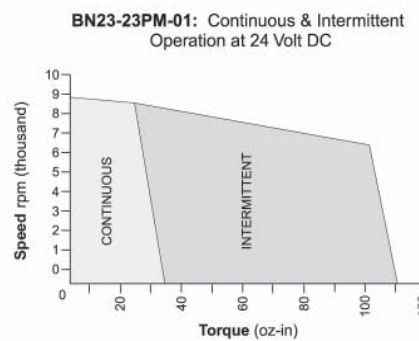
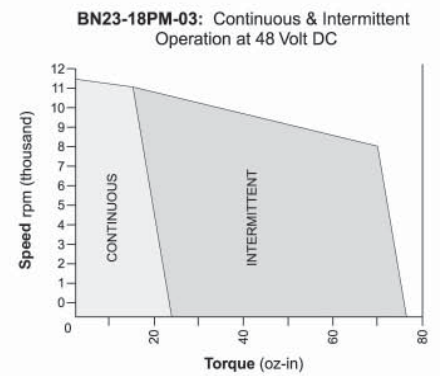
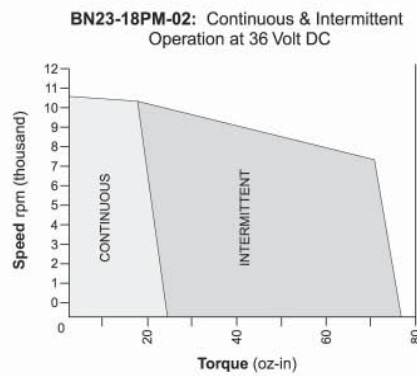
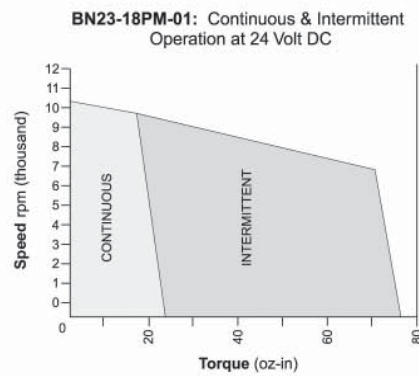
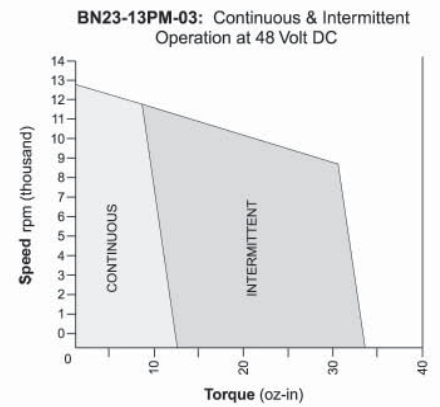
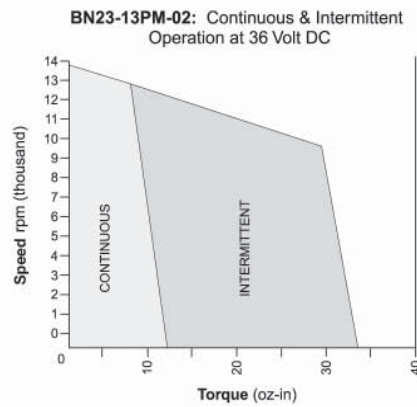
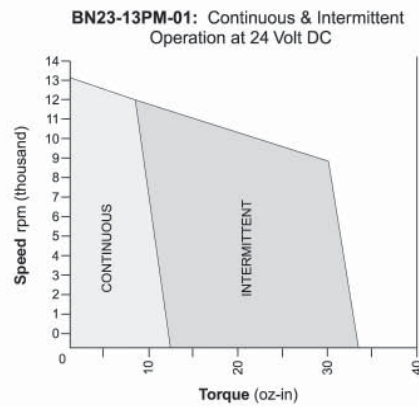
Termination Table

PIN #	CONNECTION
1	Vcc
2	GROUND
3	A COIL
4	B COIL
5	C COIL
6	S2 OUT
7	S1 OUT
8	S3 OUT



Dimensions are in inches (millimeters)

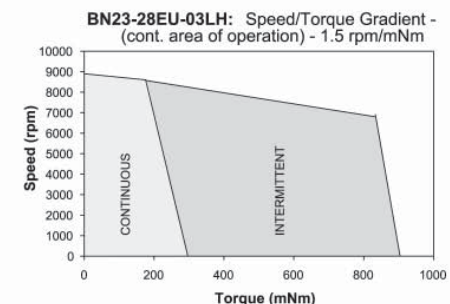
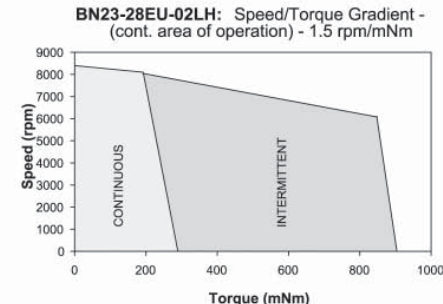
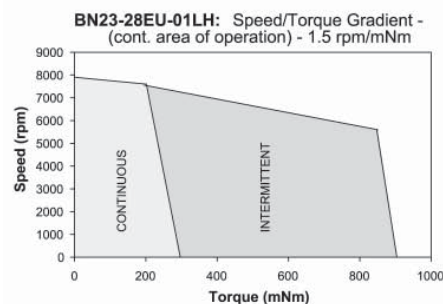
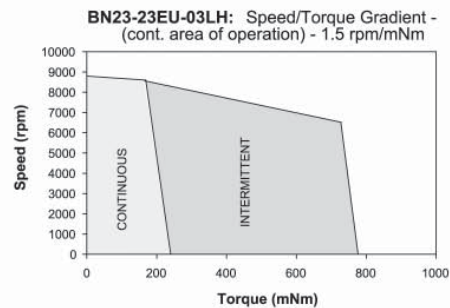
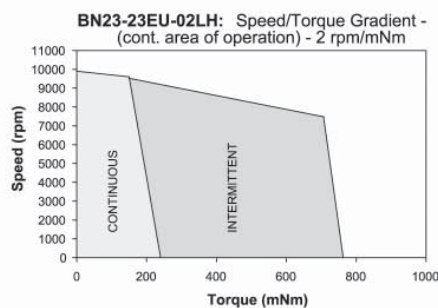
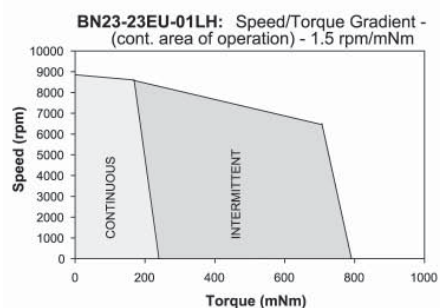
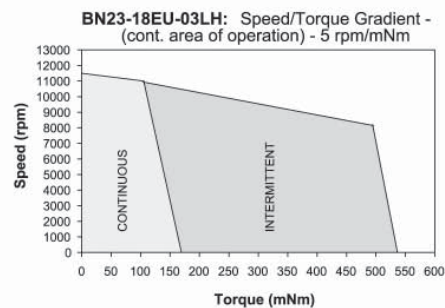
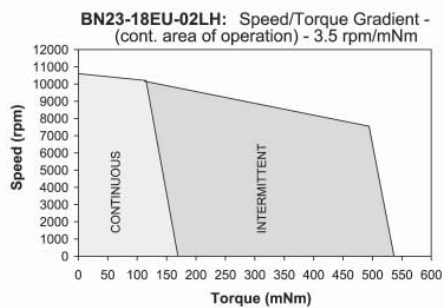
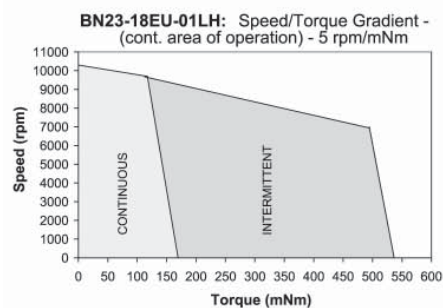
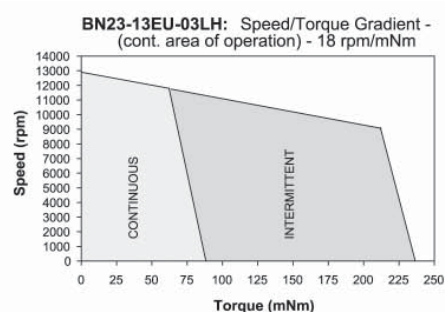
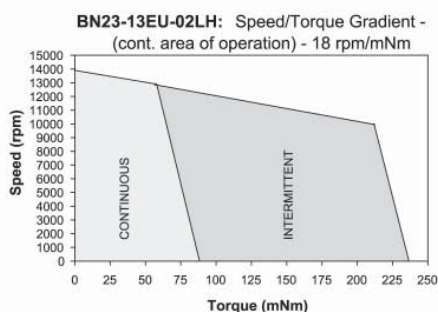
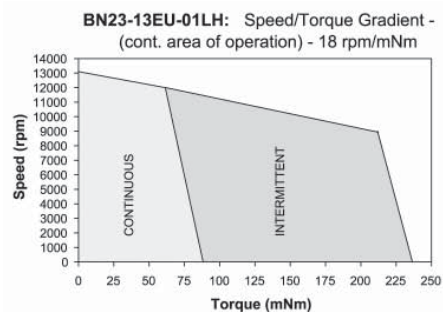
BN23 Performance Curves



Note: Intermittent operation is based on a 20% duty cycle of one minute on, four minutes off.
Please contact the factory regarding the duty cycle of your application.

Brushless Motors

BN23 EU Performance Curves



Note: Intermittent operation is based on a 20% duty cycle of one minute on, four minutes off.
Please contact the factory regarding the duty cycle of your application.

BN28 SPECIFICATIONS -

Continuous Stall Torque 43 - 108 oz-in (0.30 - 0.76 Nm)
Peak Torque 188 - 737 oz-in (1.33 - 5.2 Nm)

Part Number*		BN28-21AF- ☐ ☐ ☒ ☐ ☐			BN28-29AF- ☐ ☐ ☒ ☐ ☐			BN28-36AF- ☐ ☐ ☒ ☐ ☐			BN28-44AF- ☐ ☐ ☒ ☐ ☐		
Winding Code**		01	02	03	01	02	03	01	02	03	01	02	03
L = Length	inches	2.10			2.90			3.60			4.40		
	millimeters	53.3			73.7			91.4			111.8		
Terminal Voltage	volts DC	24.0	48.0	72.0	24.0	48.0	72.0	24.0	48.0	72.0	24.0	48.0	72.0
Peak Torque	oz-in	188.0	188.0	188.0	407.0	407.0	407.0	596.0	596.0	596.0	737.0	737.0	737.0
	Nm	1.3276	1.3276	1.3276	2.8740	2.8740	2.8740	4.2087	4.2087	4.2087	5.2043	5.2043	5.2043
Continuous Stall Torque	oz-in	43.0	44.0	46.0	71.0	74.0	72.0	93.0	95.0	93.0	106.0	108.0	105.0
	Nm	0.3036	0.3107	0.3248	0.5014	0.5226	0.5084	0.6567	0.6708	0.6567	0.7485	0.7626	0.7415
Rated Speed	RPM	9170	9230	9240	8870	8900	7890	5890	5910	5230	4660	4680	4120
	rad/sec	960	967	968	929	932	826	617	619	548	488	490	431
Rated Torque	oz-in	31	31	33	40	40	46	68	70	72	84	84	86
	Nm	0.2189	0.2189	0.2330	0.2825	0.2825	0.3248	0.4802	0.4943	0.5084	0.5932	0.5932	0.6073
Rated Current	Amps	10.26	5.13	3.63	12.67	6.33	4.29	14.31	7.35	4.51	14.25	7.13	4.35
Rated Power	watts	210.3	211.6	225.5	262.4	263.3	268.4	296.2	306.0	278.5	289.5	290.8	262.1
Torque Sensitivity	oz-in/amp	3.24	6.49	9.73	3.48	6.95	11.59	5.07	10.13	16.89	6.25	12.50	20.84
	Nm/amp	0.0229	0.0458	0.0687	0.0246	0.0491	0.0818	0.0358	0.0715	0.1193	0.0441	0.0883	0.1472
Back EMF	volts/KRPM	2.40	4.80	7.20	2.57	5.14	8.57	3.75	7.49	12.49	4.62	9.24	15.41
	volts/rad/sec	0.0229	0.0458	0.0687	0.0246	0.0491	0.0818	0.0358	0.0715	0.1193	0.0441	0.0883	0.1472
Terminal Resistance	ohms	0.14	0.51	1.08	0.07	0.25	0.72	0.10	0.36	1.05	0.12	0.47	1.38
Terminal Inductance	mH	0.18	0.72	1.62	0.11	0.43	1.19	0.17	0.69	1.92	0.24	0.97	2.69
Motor Constant	oz-in/sq.rt.watt	8.72	9.06	9.38	13.44	13.93	13.69	16.45	16.86	16.49	17.82	18.18	17.73
	Nm/sq.rt.watt	0.062	0.064	0.066	0.095	0.098	0.097	0.116	0.119	0.11645	0.12584	0.12835	0.12518
Rotor Inertia	oz-in-sec ² x10 ⁻³	2.30	2.30	2.30	4.40	4.40	4.40	6.60	6.60	6.60	8.80	8.80	8.80
	g-cm ²	162.3	162.3	162.3	310.5	310.5	310.5	465.8	465.8	465.8	621.0	621.0	621.0
Weight	oz	23.0	23.0	23.0	35.0	35.0	35.0	48.0	48.0	48.0	61.0	61.0	61.0
	g	653.2	653.2	653.2	994.0	994.0	994.0	1363.2	1363.2	1363.2	1732.4	1732.4	1732.4
# of Poles		8.0	8.0	8.0	8.0	8.0	8.0	8.0	8.0	8.0	8.0	8.0	8.0
Timing		120°	120°	120°	120°	120°	120°	120°	120°	120°	120°	120°	120°
Mech. Time Constant	ms	4.3	4.0	3.7	3.4	3.2	3.3	3.5	3.3	3.4	3.9	3.8	4.0
Electrical Time Constant	ms	1.30	1.40	1.51	1.64	1.73	1.66	1.79	1.91	1.83	1.95	2.05	1.95
Thermal Resistivity	deg. C/watt	2.9	3.0	2.9	2.5	2.6	2.6	2.2	2.2	2.3	2.0	2.0	2.1
Speed/Torque Gradient	rpm/oz-in	17.7	16.5	15.4	7.5	7.0	7.2	5.0	4.8	5.0	4.3	4.1	4.3

Notes:

- Motor mounted to a 10" x 10" x 1/4" aluminum plate, still air.
- Maximum winding temperature of 155°C.
- Typical electrical specifications at 25°C.
- Motor Terminal Voltages are representative only; motors may be operated at voltages other than those listed in the table. For assistance please contact our applications engineer.

*Many other custom mechanical options are available – consult factory.

**Many other winding options are available – consult factory.

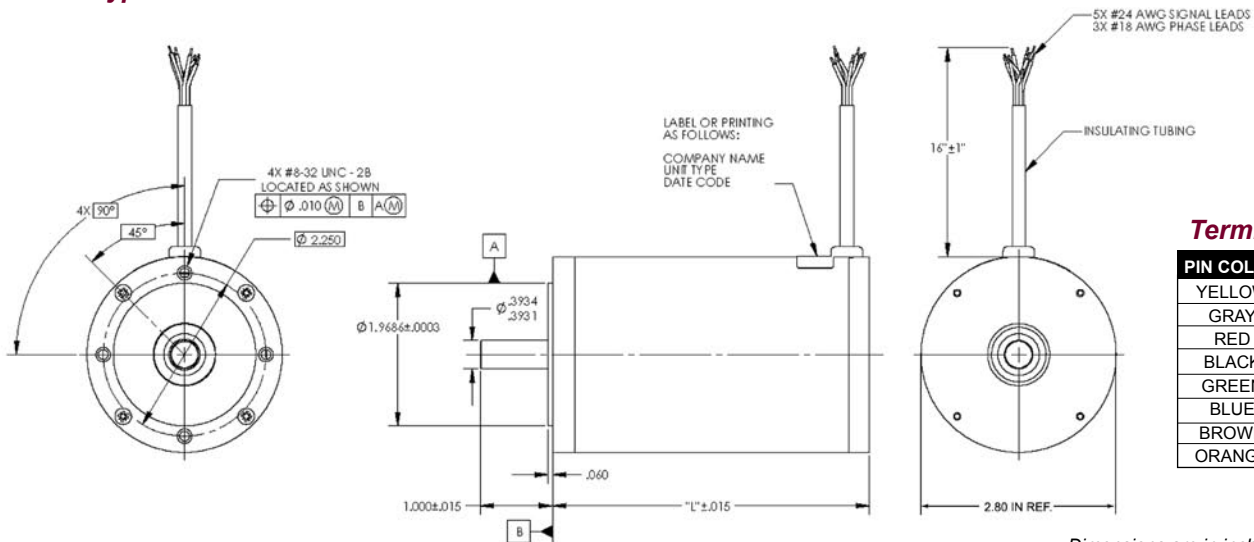
Select your options below and place their code in its corresponding block as shown on page 8.

T TERMINATION
L – Leads (std)
C – Connector
M – MS connector

F FEEDBACK OPTIONS
H – Hall Effect (std)
R – Resolver
S – Sensorless

O OTHER OPTIONS
D – Drive
E – Encoder
G – Gearhead

BN28 Typical Outline



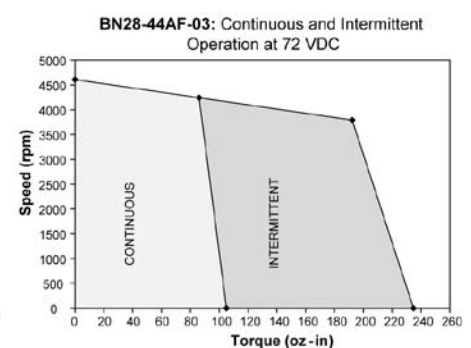
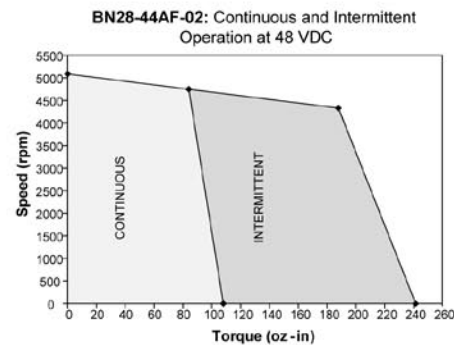
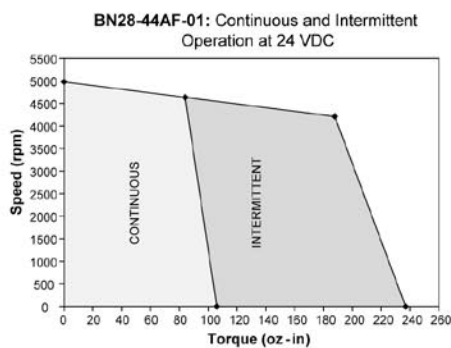
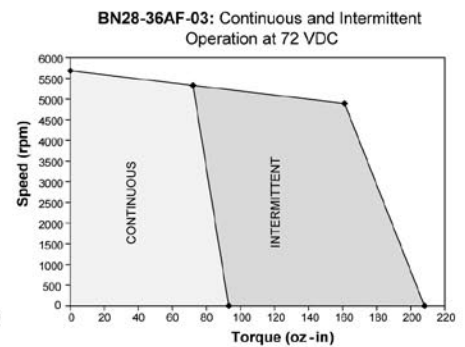
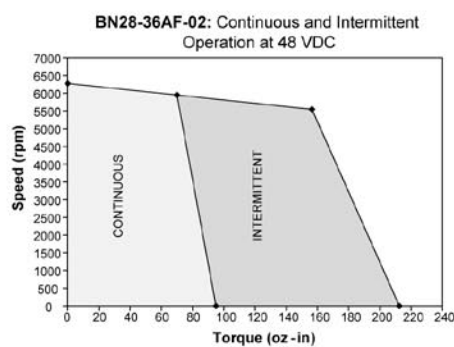
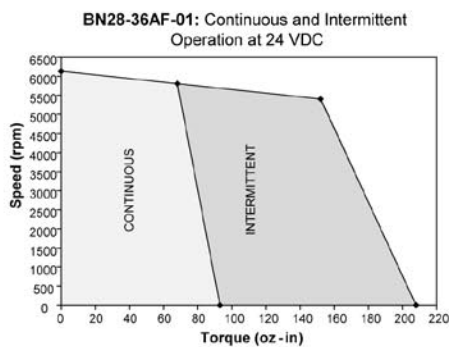
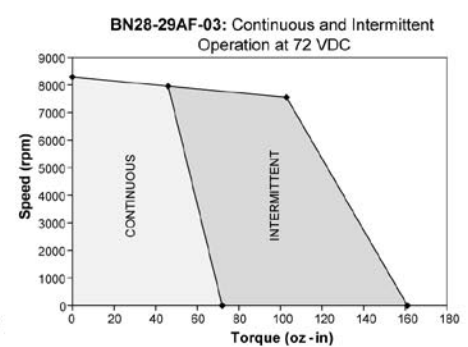
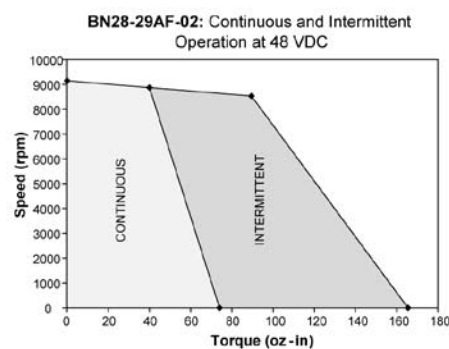
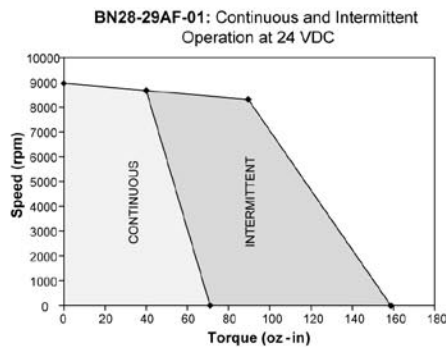
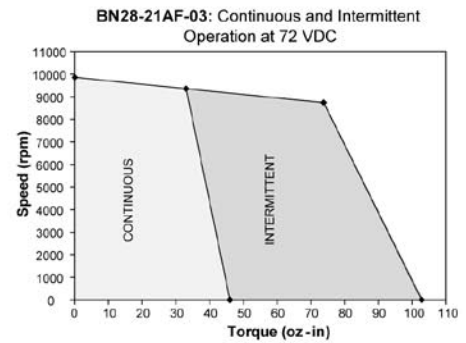
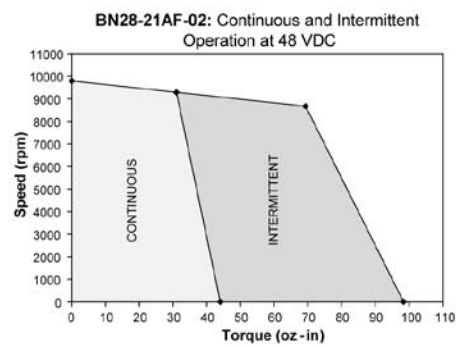
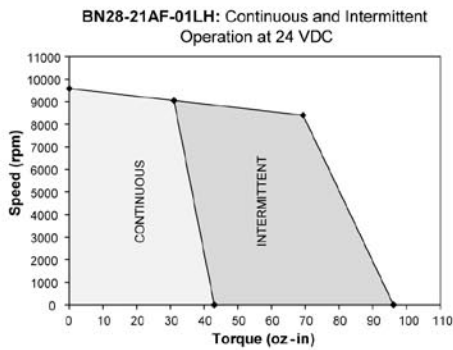
Termination Table

PIN COLOR	CONNECTION
YELLOW	V _{CC}
GRAY	GROUND
RED	A COIL
BLACK	B COIL
GREEN	C COIL
BLUE	S2 OUT
BROWN	S1 OUT
ORANGE	S3 OUT

Dimensions are in inches (millimeters)

Brushless Motors

BN28 Performance Curves



Note: Intermittent operation is based on a 20% duty cycle of one minute on, four minutes off.
Please contact the factory regarding the duty cycle of your application.

BN34 SPECIFICATIONS - Continuous Stall Torque 83 - 309 oz-in (0.587 - 2.19 Nm) Peak Torque 326 - 1445 oz-in (2.31 - 10.21 Nm)

Part Number*		BN34-25AF- ☐ ☐ ☐ ☐ ☐			BN34-35AF- ☐ ☐ ☐ ☐ ☐			BN34-45AF- ☐ ☐ ☐ ☐ ☐			BN34-55AF- ☐ ☐ ☐ ☐ ☐		
Winding Code**		01	02	03	01	02	03	01	02	03	01	02	03
L = Length	inches	2.50			3.50			4.50			5.50		
	millimeters	63.5			88.9			114.3			139.7		
Terminal Voltage	volts DC	24.0	50.0	100.0	24.0	50.0	100.0	24.0	50.0	100.0	24.0	50.0	100.0
Peak Torque	oz-in	326.0	326.0	326.0	566.0	643.0	697.0	1070.0	1070.0	1070.0	1445.0	1445.0	1445.0
	Nm	2.3020	2.3020	2.3020	3.9968	4.5405	4.9219	7.5558	7.5558	7.5558	10.2039	10.2039	10.2039
Continuous Stall Torque	oz-in	83.0	93.0	93.0	133.0	162.0	159.0	220.0	224.0	231.0	287.0	306.0	309.0
	Nm	0.5861	0.6567	0.6567	0.9392	1.144	1.1228	1.5535	1.5818	1.6312	2.0267	2.1608	2.1820
Rated Speed	RPM	7400.0	7330.0	7550.0	5916.0	6400.0	6240.0	3300.0	4710.0	4710.0	2410.0	3910.0	3920.0
	rad/sec	775	768	791	620	670	653	346	493	493	252	409	411
Rated Torque	oz-in	60.0	67.0	66.0	93.0	106.0	106.0	188.0	165.0	170.0	258.0	240.0	240.0
	Nm	0.4237	0.4731	0.4661	0.6567	0.749	0.7485	1.3276	1.1651	1.2005	1.8219	1.6948	1.6948
Rated Current	Amps	16.40	8.70	4.40	18.74	11.0	5.80	23.0	13.70	7.00	23.30	16.50	8.20
Rated Power	watts	328.0	363.0	368.0	407.0	502.0	489.0	459.0	575.0	592.0	460.0	694.0	696.0
Torque Sensitivity	oz-in/amp	4.19	8.90	17.20	5.24	9.92	21.0	9.20	13.80	27.70	12.40	16.60	33.20
	Nm/amp	0.0296	0.0628	0.1215	0.0370	0.0701	0.1483	0.0650	0.0974	0.1956	0.0876	0.1172	0.2344
Back EMF	volts/KRPM	3.10	6.50	12.80	3.88	7.34	15.50	6.83	10.20	20.50	9.20	12.30	24.50
	volts/rad/sec	0.0296	0.0628	0.1215	0.0370	0.070	0.1483	0.0650	0.0974	0.1956	0.0876	0.1172	0.2344
Terminal Resistance	ohms	0.069	0.251	0.941	0.057	0.147	0.575	0.069	0.147	0.552	0.086	0.135	0.504
Terminal Inductance	mH	0.129	0.575	2.180	0.143	0.430	1.570	0.200	0.450	1.800	0.271	0.482	1.930
Motor Constant	oz-in/sq.rt.watt	15.95	17.76	17.73	21.95	25.87	27.69	35.02	35.99	37.28	42.28	45.18	46.77
	Nm/sq.rt.watt	0.11264	0.12544	0.12521	0.15499	0.183	0.19556	0.24732	0.25417	0.26328	0.29859	0.31904	0.33023
Rotor Inertia	oz-in-sec ² x10 ⁻³	6.00	6.00	6.00	12.00	12.00	12.00	18.00	18.00	18.00	24.00	24.00	24.00
	g-cm ²	423.4	423.4	423.4	846.8	846.8	846.8	1270.3	1270.3	1270.3	1693.7	1693.7	1693.7
Weight	oz	37.0	37.0	37.0	62.0	62.0	62.0	88.0	88.0	88.0	115.0	115.0	115.0
	g	1050.8	1050.8	1050.8	1760.8	1760.8	1760.8	2499.2	2499.2	2499.2	3266.0	3266.0	3266.0
# of Poles		8.0	8.0	8.0	8.0	8.0	8.0	8.0	8.0	8.0	8.0	8.0	8.0
Timing		120°	120°	120°	120°	120°	120°	120°	120°	120°	120°	120°	120°
Mech. Time Constant	ms	3.3	2.7	2.7	3.5	2.5	2.2	2.1	2.0	1.8	1.9	1.7	1.6
Electrical Time Constant	ms	1.87	2.29	2.32	2.51	2.90	2.73	2.90	3.06	3.26	3.15	3.57	3.83
Thermal Resistivity	deg. C/watt	1.6	1.5	1.5	2.5	1.84	1.2	1.1	1.0	1.0	1.1	0.8	0.8
Speed/Torque Gradient	rpm/oz-in	5.3	4.3	4.3	2.8	2.8	1.8	1.1	1.0	1.0	0.8	0.7	0.6

Notes:

- Motor mounted to a 10" x 10" x 1/4" aluminum plate, still air.
- Maximum winding temperature of 155°C.
- Typical electrical specifications at 25°C.
- Motor Terminal Voltages are representative only; motors may be operated at voltages other than those listed in the table. For assistance please contact our applications engineer.

*Many other custom mechanical options are available – consult factory.

**Many other winding options are available – consult factory.

Select your options below and place their code in its corresponding block as shown on page 8.

TERMINATION

- L – Leads (std)
- C – Connector
- M – MS connector

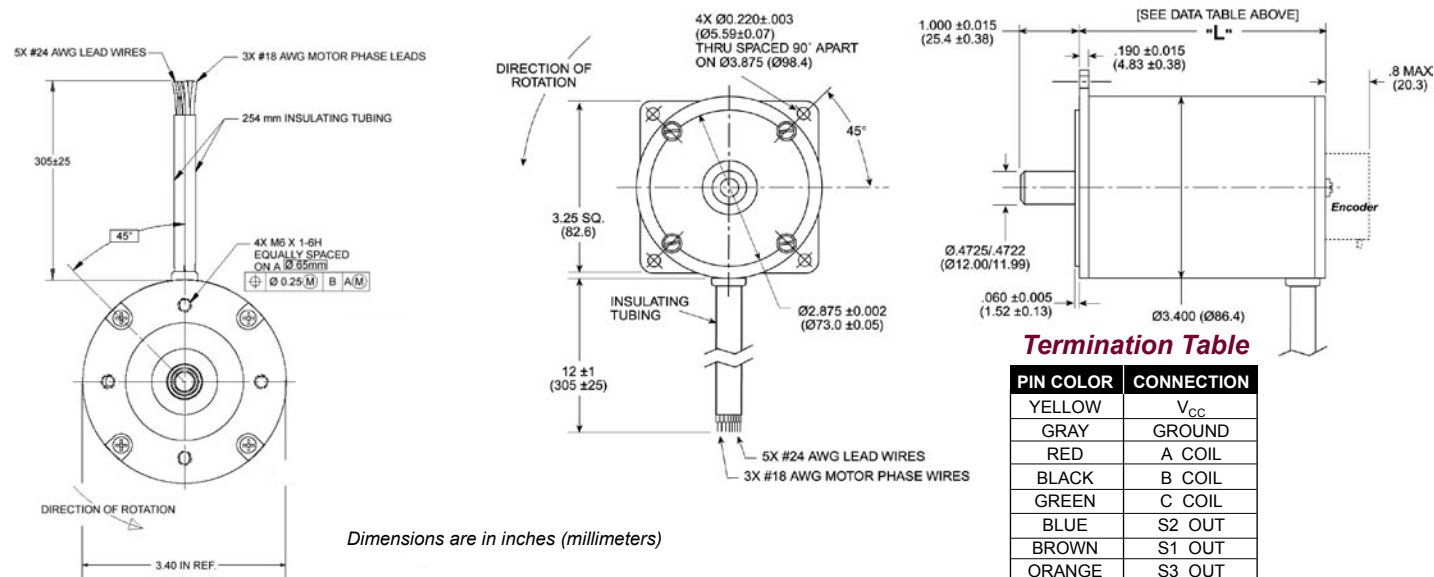
FEEDBACK OPTIONS

- H – Hall Effect (std)
- R – Resolver
- S – Sensorless

OTHER OPTIONS

- D – Drive
- E – Encoder
- G – Gearhead

BN34 Typical Outline



Brushless Motors

BN34 EU SPECIFICATIONS -

Continuous Stall Torque 83 - 309 oz-in (0.587 - 2.19 Nm)
Peak Torque 326 - 1445 oz-in (2.31 - 10.21 Nm)

Part Number*		BN34-25EU-   			BN34-35EU-   			BN34-45EU-   			BN34-55EU-   		
Winding Code**		01	02	03	01	02	03	01	02	03	01	02	03
L = Length	inches	2.50			3.50			4.50			5.50		
	millimeters	63.5			88.9			114.3			139.7		
Terminal Voltage	volts DC	24	50	100	24	50	100	24	50	100	24	50	100
Peak Torque	oz-in	326	326	326	697	697	697	1070	1070	1070	1445	1445	1445
	Nm	2.31	2.31	2.31	4.93	4.93	4.93	7.56	7.56	7.56	10.21	10.21	10.21
Continuous Stall Torque	oz-in	83	93	93	152	159	159	220	224	231	287	306	309
	Nm	0.587	0.657	0.657	1.074	1.13	1.13	1.54	1.59	1.64	2.03	2.17	2.19
Rated Speed	RPM	7400	7330	7550	5160	5930	6240	3300	4710	4710	2410	3910	3920
	rad/sec	775	768	791	541	621	654	346	494	494	253	410	411
Rated Torque	oz-in	60	67	66	117	110	106	188	165	170	258	240	240
	Nm	0.424	0.474	0.467	0.827	0.777	0.749	1.33	1.17	1.20	1.83	1.70	1.70
Rated Current	Amps	16.4	8.7	4.4	22.3	11.5	5.8	23.0	13.7	7.0	23.3	16.5	8.2
Rated Power	watts	328	363	368	446	482	489	459	575	592	460	694	696
Torque Sensitivity	oz-in/amp	4.19	8.90	17.2	6.01	11.0	21.0	9.20	13.8	27.7	12.40	16.6	33.2
	Nm/amp	0.0296	0.0621	0.123	0.0424	0.0774	0.148	0.0653	0.0974	0.196	0.0879	0.118	0.234
Back EMF	volts/KRPM	3.10	6.50	12.8	4.44	8.10	15.5	6.83	10.2	20.5	9.20	12.3	24.5
	volts/rad/sec	0.0296	0.0621	0.123	0.0424	0.0774	0.148	0.0653	0.0974	0.196	0.0879	0.118	0.234
Terminal Resistance	ohms	0.069	0.251	0.941	0.053	0.160	0.575	0.069	0.147	0.552	0.086	0.135	0.504
Terminal Inductance	mH	0.129	0.575	2.18	0.129	0.432	1.57	0.200	0.450	1.80	0.271	0.482	1.93
Motor Constant	oz-in/sq.rt.watt	17.7	18.2	17.9	30.1	28.7	28.0	38.9	37.8	37.7	46.1	47.4	47.4
	Nm/sq.rt.watt	0.125	0.129	0.127	0.213	0.203	0.198	0.275	0.267	0.267	0.326	0.335	0.335
Rotor Inertia	oz-in-sec ²	0.006	0.006	0.006	0.012	0.012	0.012	0.018	0.018	0.018	0.024	0.024	0.024
	g-cm ²	424	424	424	848	848	848	1271	1271	1271	1695	1695	1695
Weight	oz	37	37	37	62	62	62	88	88	88	115	115	115
	g	1049	1049	1049	1758	1758	1758	2495	2495	2495	3261	3261	3261

Notes:

- Motor mounted to a 10" x 10" x 1/4" aluminum plate, still air.
- Maximum winding temperature of 155°C.
- Typical electrical specifications at 25°C.
- Motor Terminal Voltages are representative only; motors may be operated at voltages other than those listed in the table. For assistance please contact our applications engineer.

*Many other custom mechanical options are available – consult factory.

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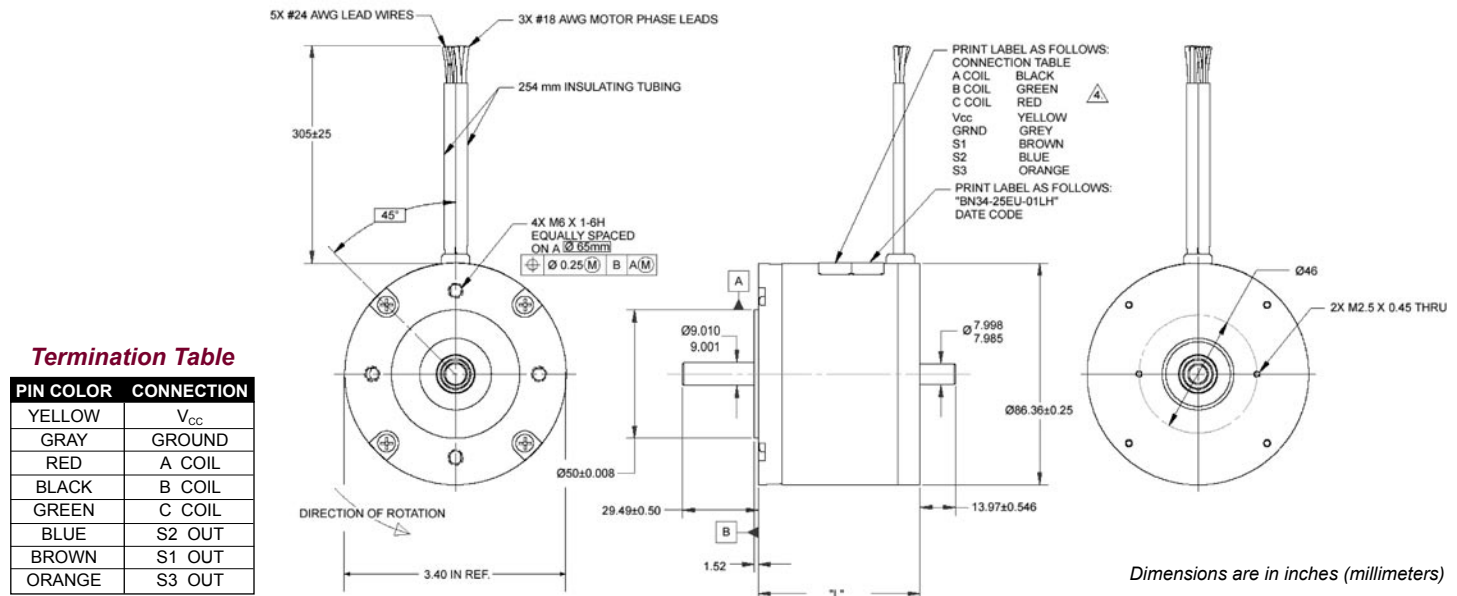
Select your options below and place their code in its corresponding block as shown on page 8.

T TERMINATION
L – Leads (std)
C – Connector
M – MS connector

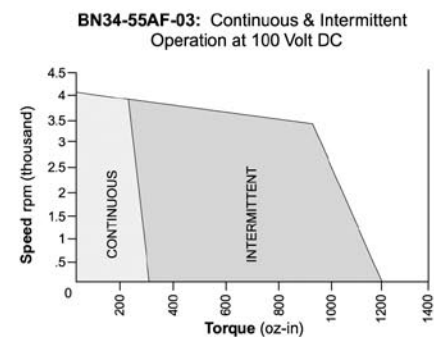
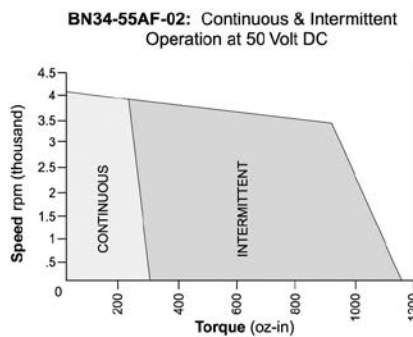
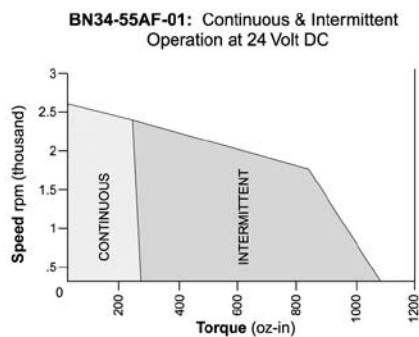
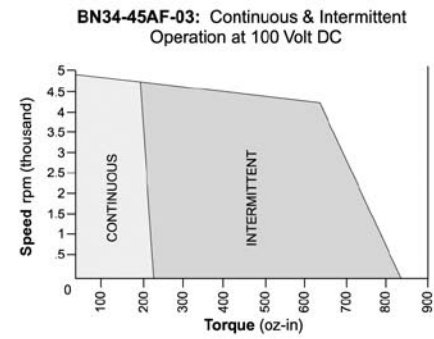
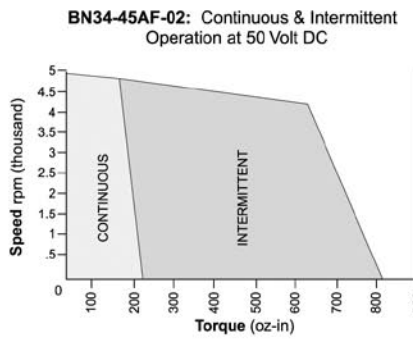
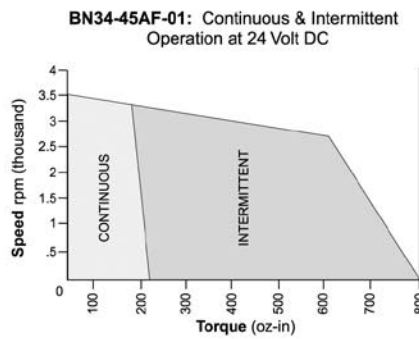
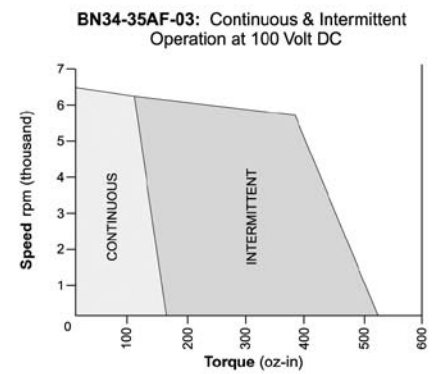
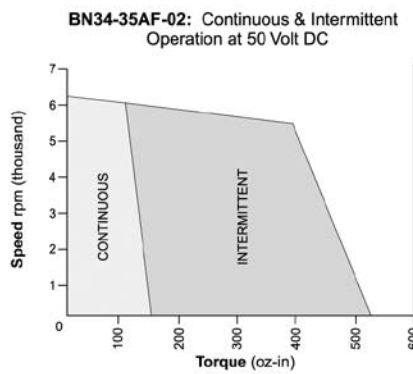
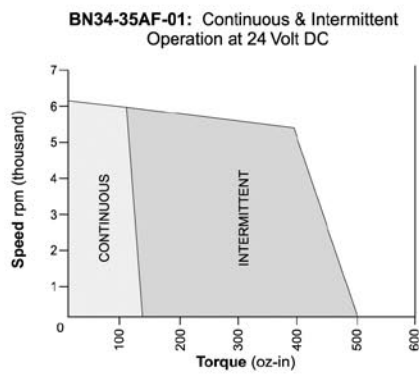
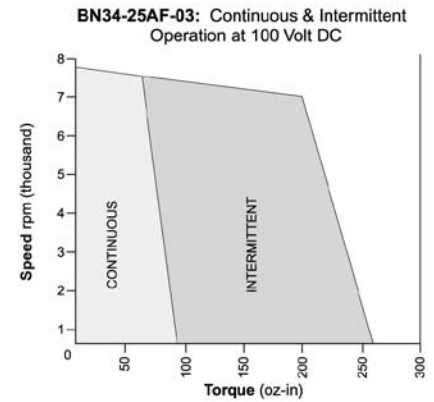
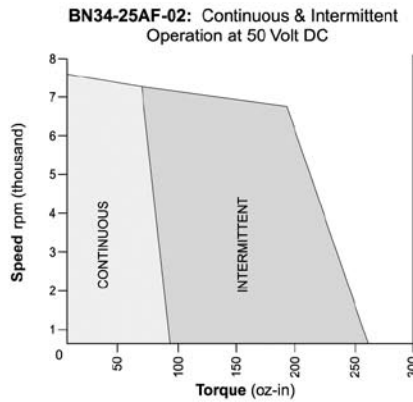
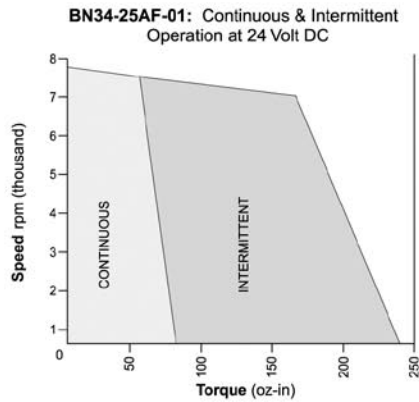
F FEEDBACK OPTIONS
H – Hall Effect (std)
R – Resolver
S – Sensorless

O OTHER OPTIONS
D – Drive
E – Encoder
G – Gearhead

BN34 EU Typical Outline



BN34 Performance Curves

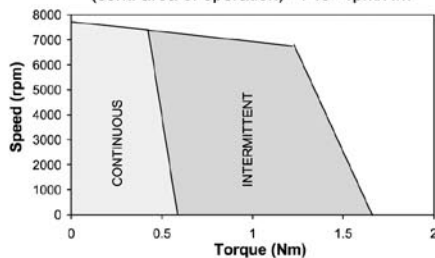


Note: Intermittent operation is based on a 20% duty cycle of one minute on, four minutes off.
Please contact the factory regarding the duty cycle of your application.

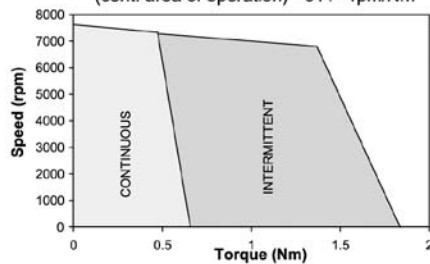
Brushless Motors

BN34 EU Performance Curves

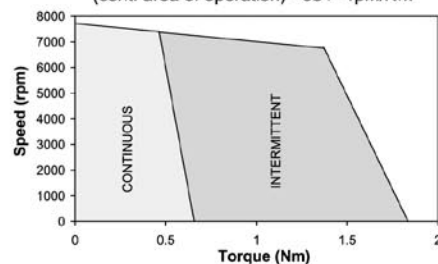
BN34-25EU-01LH: Speed/Torque Gradient -
(cont. area of operation) - 748 - rpm/Nm



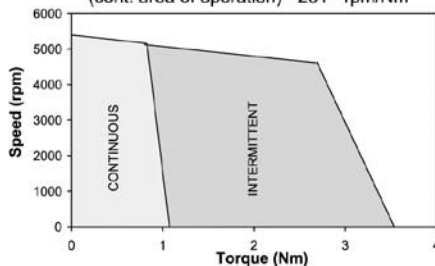
BN34-25EU-02LH: Speed/Torque Gradient -
(cont. area of operation) - 611 - rpm/Nm



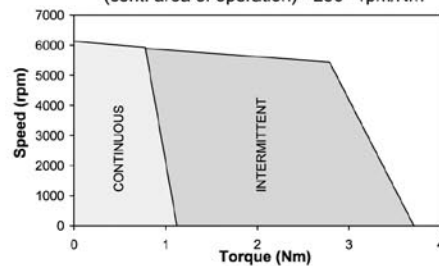
BN34-25EU-03LH: Speed/Torque Gradient -
(cont. area of operation) - 684 - rpm/Nm



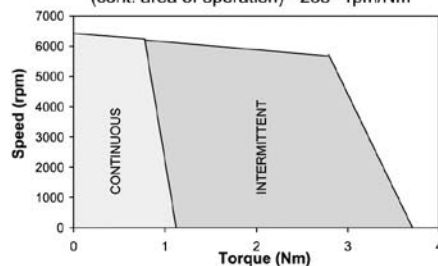
BN34-35EU-01LH: Speed/Torque Gradient -
(cont. area of operation) - 281 - rpm/Nm



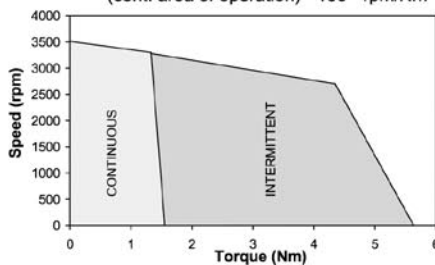
BN34-35EU-02LH: Speed/Torque Gradient -
(cont. area of operation) - 256 - rpm/Nm



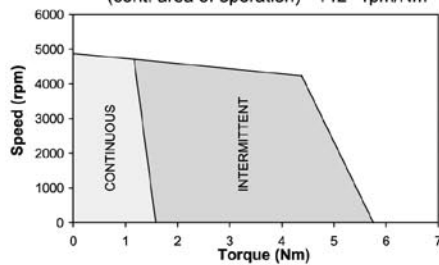
BN34-35EU-03LH: Speed/Torque Gradient -
(cont. area of operation) - 233 - rpm/Nm



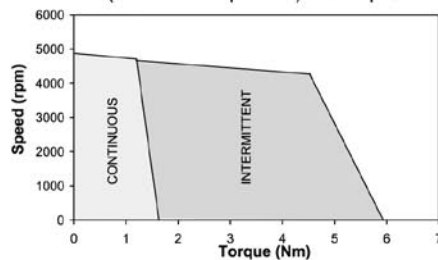
BN34-45EU-01LH: Speed/Torque Gradient -
(cont. area of operation) - 158 - rpm/Nm



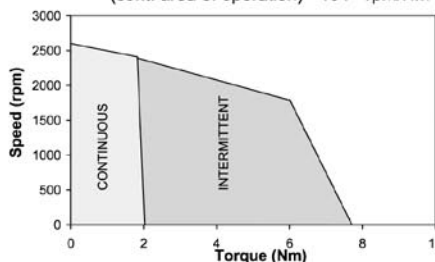
BN34-45EU-02LH: Speed/Torque Gradient -
(cont. area of operation) - 142 - rpm/Nm



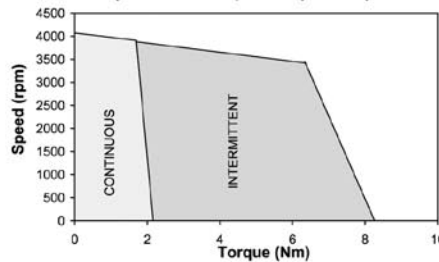
BN34-45EU-03LH: Speed/Torque Gradient -
(cont. area of operation) - 137 - rpm/Nm



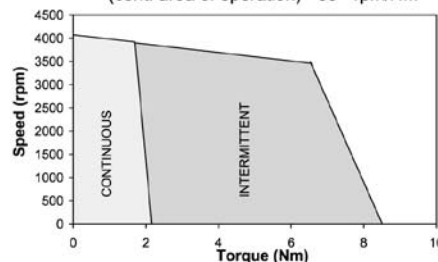
BN34-55EU-01LH: Speed/Torque Gradient -
(cont. area of operation) - 104 - rpm/Nm



BN34-55EU-02LH: Speed/Torque Gradient -
(cont. area of operation) - 95 - rpm/Nm



BN34-55EU-03LH: Speed/Torque Gradient -
(cont. area of operation) - 89 - rpm/Nm

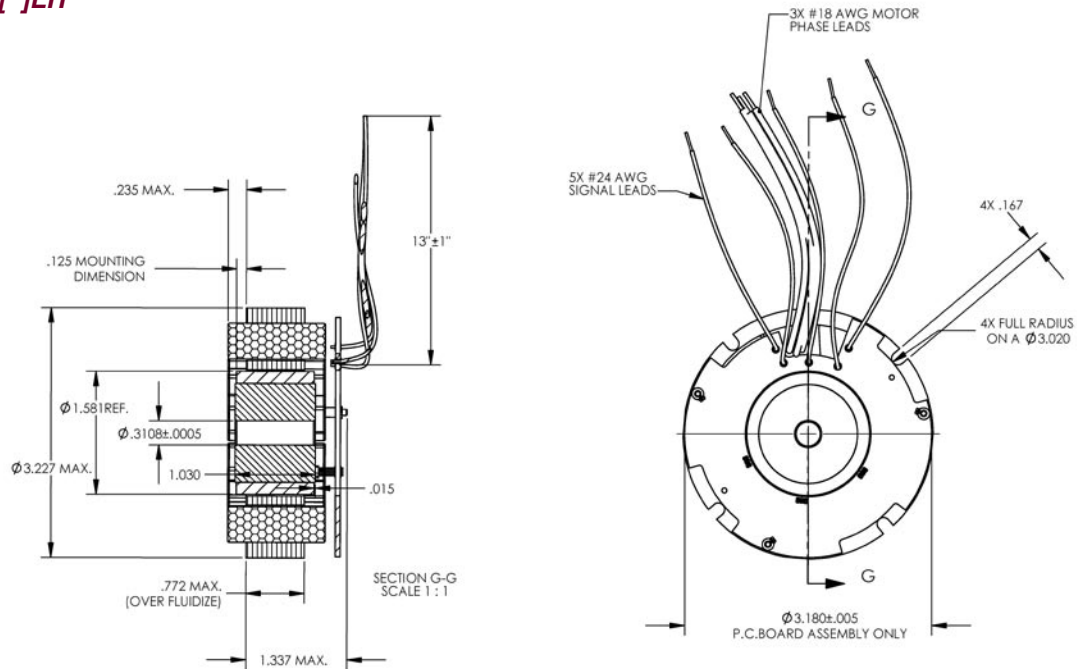


Note: Intermittent operation is based on a 20% duty cycle of one minute on, four minutes off.
Please contact the factory regarding the duty cycle of your application.

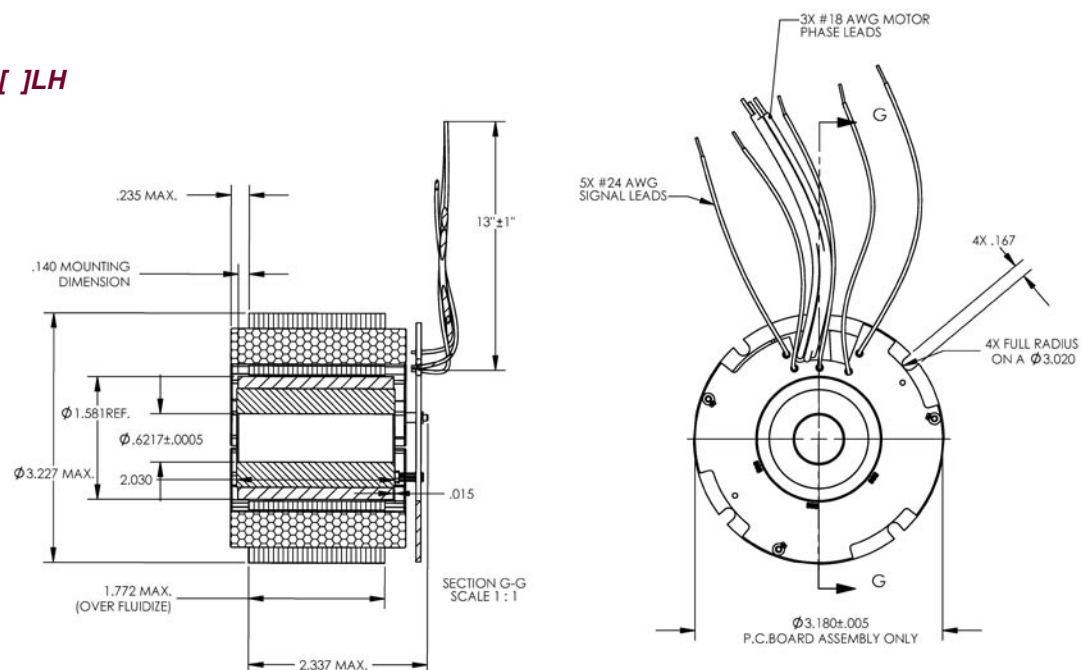
BN34 Part-Set

In addition to the housed motors, the BN34 is also available as a rotor-stator part-set. Part-sets are often used when the application or apparatus involves a higher level assembly where the motor's rotor and stator can be integrated into existing housings or casting. Part-sets are more economical than the housed motor due to the elimination of the motor housing, end caps, bearings and shafts. Another economic advantage is that the rotor and stator assembly may be purchased separately for either spare or replacement parts. Part-sets are available in all standard lengths and winding codes. The following drawings depict our standard BN34 part-sets. For application assistance call 800-577-8685, ext. 256.

BN34-25ZP[][]LH

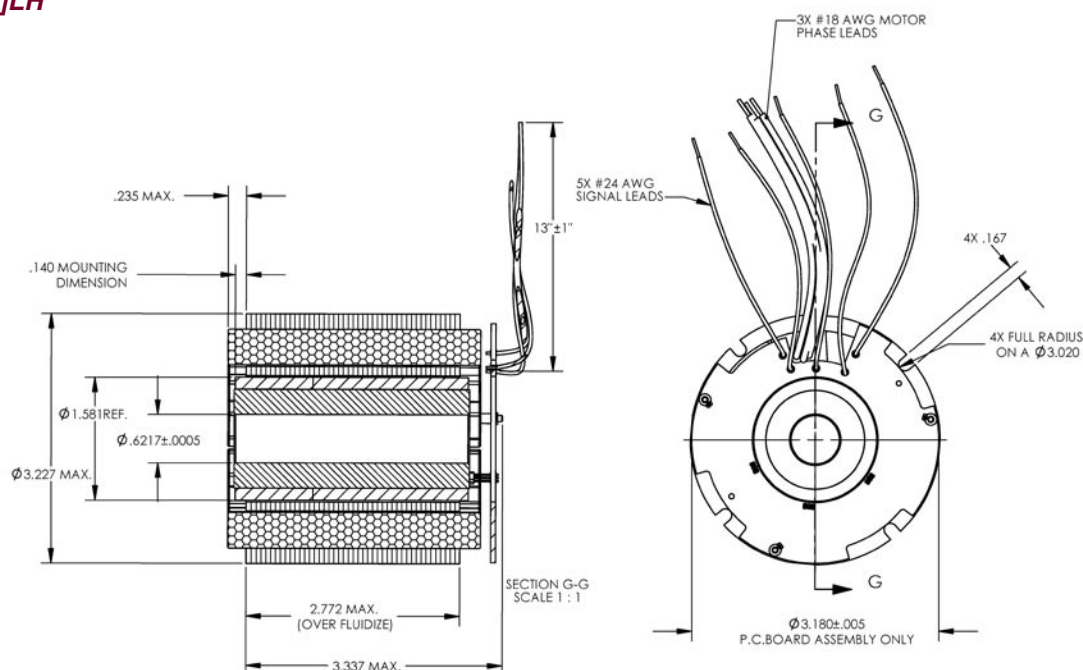


BN34-35ZP[][]LH

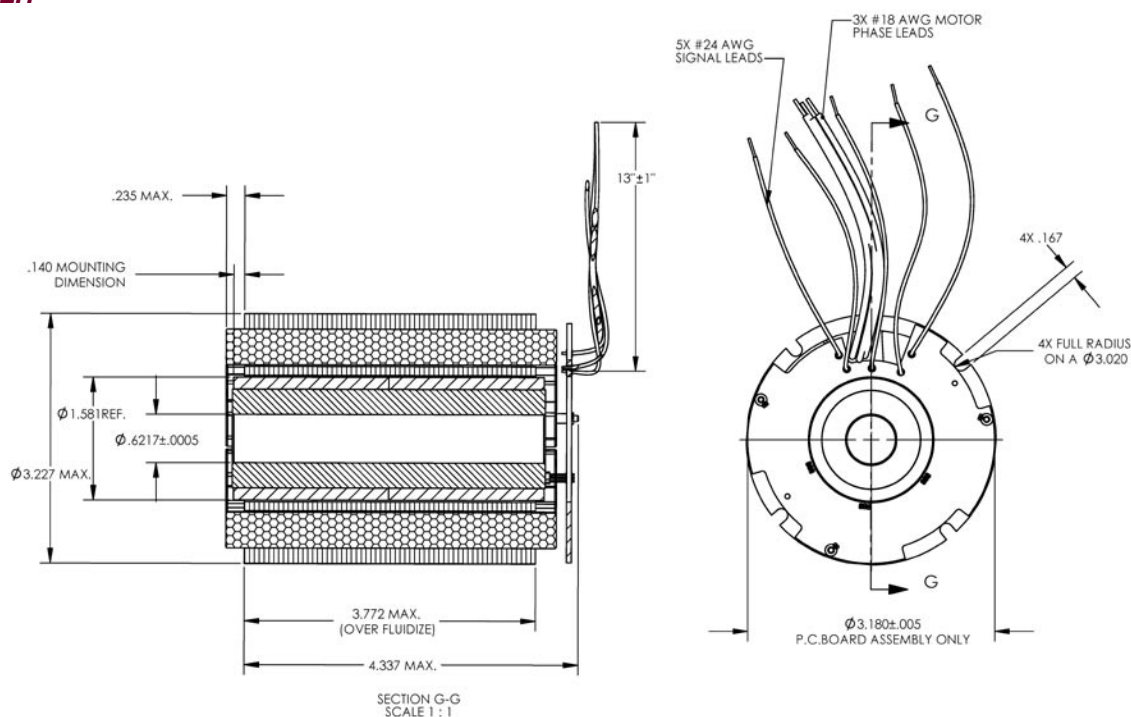


Brushless Motors

BN34-45ZP[][]LH



BN34-55ZP[][]LH



Notes:

1. The basic part-set consists of a wound stator, rotor core and magnet, and Hall-effect printed circuit board. Shafts and bearings can be furnished if necessary. Contact the factory for assistance.
2. The pe□ the housed motor.

BN42 SPECIFICATIONS -

Continuous Stall Torque 144 - 519 oz-in (1.02 - 3.67 Nm)
Peak Torque 609 - 2560 oz-in (4.30 - 18.1 Nm)

Part Number*		BN42-23AF- ☐ ☐ ☐ ☐ ☐			BN42-33AF- ☐ ☐ ☐ ☐ ☐			BN42-43AF- ☐ ☐ ☐ ☐ ☐			BN42-53AF- ☐ ☐ ☐ ☐ ☐		
Winding Code**		01	02	03	01	02	03	01	02	03	01	02	03
L = Length	inches	2.30			3.30			4.30			5.30		
	millimeters	58.4			83.8			109.2			134.6		
Terminal Voltage	volts DC	24.0	50.0	100.0	24.0	50.0	100.0	24.0	50.0	100.0	24.0	50.0	100.0
Peak Torque	oz-in	609.0	609.0	609.0	1248.0	1248.0	1248.0	1906.0	1906.0	1906.0	2560.0	2560.0	2560.0
	Nm	4.3005	4.3005	4.3005	8.8128	8.8128	8.8128	13.4592	13.4592	13.4592	18.0774	18.0774	18.0774
Continuous Stall Torque	oz-in	144.0	156.0	155.0	266.0	281.0	287.0	387.0	398.0	407.0	496.0	510.0	519.0
	Nm	1.0169	1.1016	1.0945	1.8784	1.9843	2.0267	2.7328	2.8105	2.8740	3.5025	3.6014	3.6649
Rated Speed	RPM	6050.0	5950.0	6140.0	3710.0	4710.0	4710.0	2380.0	3840.0	3840.0	1740.0	2820.0	2820.0
	rad/sec	634	623	643	389	493	493	249	402	402	182	295	295
Rated Torque	oz-in	102.0	113.0	110.0	213.0	198.0	200.0	340.0	290.0	296.0	451.0	413.0	419.0
	Nm	0.7203	0.7979	0.7768	1.5041	1.3982	1.4123	2.4009	2.0478	2.0902	3.1847	2.9164	2.9588
Rated Current	Amps	22.60	11.70	5.90	28.90	16.20	8.20	29.70	19.20	9.80	29.20	20.20	10.20
Rated Power	watts	456.0	497.0	499.0	584.0	690.0	697.0	598.0	824.0	841.0	580.0	861.0	874.0
Torque Sensitivity	oz-in/amp	5.20	11.00	21.40	8.41	14.00	28.00	12.90	17.20	34.30	17.40	23.10	46.30
	Nm/amp	0.0367	0.0777	0.1511	0.0594	0.0989	0.1977	0.0911	0.1215	0.2422	0.1229	0.1631	0.3269
Back EMF	volts/KRPM	3.80	8.20	15.80	6.22	10.40	20.70	9.52	12.70	25.40	12.80	17.10	34.20
	volts/rad/sec	0.0367	0.0777	0.1511	0.0594	0.0989	0.1977	0.0911	0.1215	0.2422	0.1229	0.1631	0.3269
Terminal Resistance	ohms	0.040	0.154	0.584	0.039	0.095	0.364	0.052	0.084	0.320	0.065	0.106	0.408
Terminal Inductance	mH	0.090	0.408	1.540	0.115	0.318	1.270	0.178	0.316	1.260	0.241	0.428	1.710
Motor Constant	oz-in/sq.rt.watt	26.00	28.03	28.00	42.59	45.42	46.41	56.57	59.35	60.63	68.25	70.95	72.49
	Nm/sq.rt.watt	0.18360	0.19794	0.19775	0.30072	0.32075	0.32772	0.39947	0.41907	0.42817	0.48194	0.50102	0.51186
Rotor Inertia	oz-in-sec ² x10 ⁻³	18.00	18.00	18.00	35.00	35.00	35.00	52.00	52.00	52.00	70.00	70.00	70.00
	g-cm ²	1270.3	1270.3	1270.3	2470.0	2470.0	2470.0	3669.6	3669.6	3669.6	4939.9	4939.9	4939.9
Weight	oz	65.0	65.0	65.0	104.0	104.0	104.0	143.0	143.0	143.0	182.0	182.0	182.0
	g	1846.0	1846.0	1846.0	2953.6	2953.6	2953.6	4061.2	4061.2	4061.2	5168.8	5168.8	5168.8
# of Poles		8.0	8.0	8.0	8.0	8.0	8.0	8.0	8.0	8.0	8.0	8.0	8.0
Timing		120°	120°	120°	120°	120°	120°	120°	120°	120°	120°	120°	120°
Mech. Time Constant	ms	3.8	3.2	3.2	2.7	2.4	2.3	2.3	2.1	2.0	2.1	2.0	1.9
Electrical Time Constant	ms	2.25	2.65	2.64	2.95	3.35	3.49	3.42	3.76	3.94	3.71	4.04	4.19
Thermal Resistivity	deg. C/watt	1.2	1.2	1.2	1.0	0.9	0.9	0.9	0.8	0.8	0.9	0.7	0.7
Speed/Torque Gradient	rpm/oz-in	2.0	1.7	1.7	0.7	0.7	0.6	0.4	0.4	0.4	0.3	0.3	0.3

Notes:

- Motor mounted to a 10" x 10" x 1/4" aluminum plate, still air.
- Maximum winding temperature of 155°C.
- Typical electrical specifications at 25°C.
- Motor Terminal Voltages are representative only; motors may be operated at voltages other than those listed in the table. For assistance please contact our applications engineer.

*Many other custom mechanical options are available – consult factory.

**Many other winding options are available – consult factory.

Select your options below and place their code in its corresponding block as shown on page 8.

TERMINATION

- L – Leads (std)
C – Connector
M – MS connector

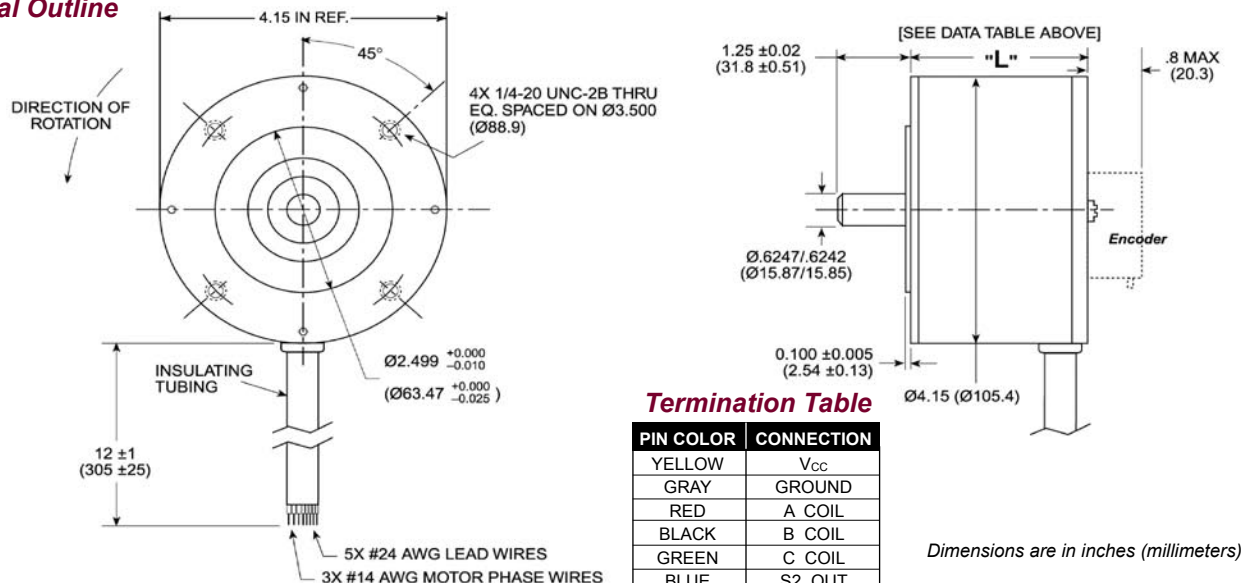
FEEDBACK OPTIONS

- H – Hall Effect (std)
R – Resolver
S – Sensorless

OTHER OPTIONS

- D – Drive
E – Encoder
G – Gearhead

BN42 Typical Outline



Note: An optional 4.15 (105.4) square front end cap is available.

Brushless Motors

BN42 EU SPECIFICATIONS - Continuous Stall Torque 144 - 519 oz-in (1.02 - 3.67 Nm)
Peak Torque 609 - 2560 oz-in (4.30 - 18.1 Nm)

Part Number*		BN42-23EU- T F O			BN42-33EU- T F O				BN42-43EU- T F O			BN42-53EU- T F O		
Winding Code**		01	02	03	01	02	03		01	02	03	01	02	03
L = Length	inches	2.30			3.30				4.30			5.30		
	millimeters	58.5			83.9				109.3			134.7		
Terminal Voltage	volts DC	24	50	100	24	50	100		24	50	100	24	50	100
Peak Torque	oz-in	609	609	609	1248	1248	1248		1906	1906	1906	2560	2560	2560
	Nm	4.30	4.30	4.30	8.82	8.82	8.82		13.5	13.5	13.5	18.1	18.1	18.1
Continuous Stall Torque	oz-in	144	156	155	266	281	287		387	398	407	496	510	519
	Nm	1.02	1.11	1.10	1.88	1.99	2.03		2.74	2.81	2.88	3.51	3.61	3.67
Rated Speed	RPM	6050	5950	6140	3710	4710	4710		2380	3840	3840	1740	2820	2820
	rad/sec	634	623	643	389	494	494		250	403	403	183	296	296
Rated Torque	oz-in	102	113	110	213	198	200		340	290	296	451	413	419
	Nm	0.721	0.798	0.777	1.51	1.40	1.42		2.41	2.05	2.09	3.19	2.92	2.96
Rated Current	Amps	22.6	11.7	5.9	28.9	16.2	8.2		29.7	19.2	9.8	29.2	20.2	10.2
Rated Power	watts	456	497	499	584	690	697		598	824	841	580	861	874
Torque Sensitivity	oz-in/amp	5.20	11.0	21.4	8.41	14.0	28.0		12.9	17.2	34.3	17.4	23.1	46.3
	Nm/amp	0.0363	0.0783	0.151	0.0594	0.0992	0.198		0.0909	0.122	0.243	0.123	0.164	0.327
Back EMF	volts/KRPM	3.80	8.20	15.8	6.22	10.4	20.7		9.52	12.7	25.4	12.8	17.1	34.2
	volts/rad/sec	0.0363	0.0783	0.151	0.0594	0.0992	0.198		0.0909	0.122	0.243	0.123	0.164	0.327
Terminal Resistance	ohms	0.040	0.154	0.584	0.039	0.095	0.364		0.052	0.084	0.320	0.065	0.106	0.408
Terminal Inductance	mH	0.090	0.408	1.54	0.115	0.318	1.27		0.178	0.316	1.26	0.241	0.428	1.71
Motor Constant	oz-in/sq.rt.watt	27.8	28.6	28.2	45.7	46.8	46.8		59.5	61.2	61.1	71.0	73.0	72.9
	Nm/sq.rt.watt	0.197	0.202	0.199	0.323	0.331	0.331		0.421	0.433	0.432	0.502	0.516	0.515
Rotor Inertia	oz-in-sec ²	0.018	0.018	0.018	0.035	0.035	0.035		0.052	0.052	0.052	0.070	0.070	0.070
	g-cm ²	1271	1271	1271	2472	2472	2472		3672	3672	3672	4943	4943	4943
Weight	oz	65	65	65	104	104	104		143	143	143	182	182	182
	g	1843	1843	1843	2949	2949	2949		4054	4054	4054	5160	5160	5160

- Notes:
1. Motor mounted to a 10" x 10" x 1/4" aluminum plate, still air.
 2. Maximum winding temperature of 155°C.
 3. Typical electrical specifications at 25°C.
 4. Motor Terminal Voltages are representative only; motors may be operated at voltages other than those listed in the table. For assistance please contact our applications engineer.

*Many other custom mechanical options are available – consult factory.
**Many other winding options are available – consult factory.

Select your options below and place their code in its corresponding block as shown on page 8.

- T

TERMINATION

L – Leads (std)

C – Connector

M – MS connector
- F

FEEDBACK OPTIONS

H – Hall Effect (std)

R – Resolver

S – Sensorless
- O

OTHER OPTIONS

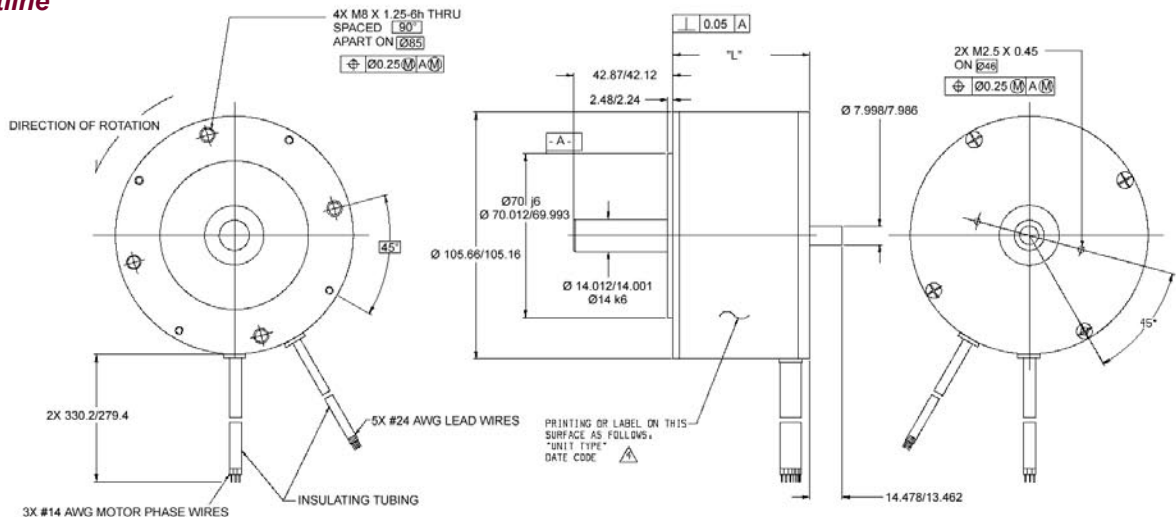
D – Drive

E – Encoder

G – Gearhead

BN42 EU Typical Outline

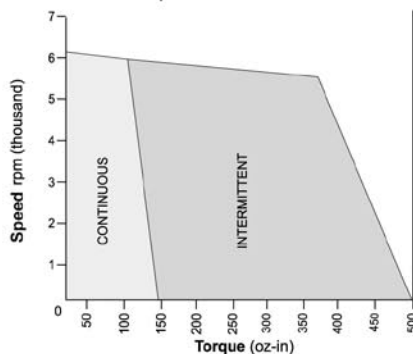
Termination Table	
PIN COLOR	CONNECTION
YELLOW	V _{CC}
GRAY	GROUND
RED	A COIL
BLACK	B COIL
GREEN	C COIL
BLUE	S2 OUT
BROWN	S1 OUT
ORANGE	S3 OUT



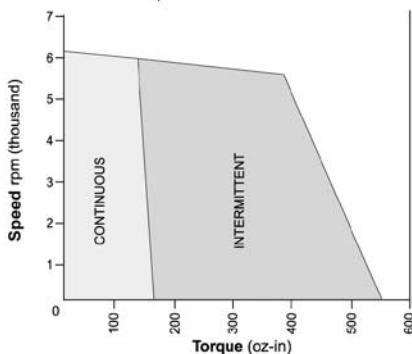
Dimensions are in inches (millimeters)

BN42 Performance Curves

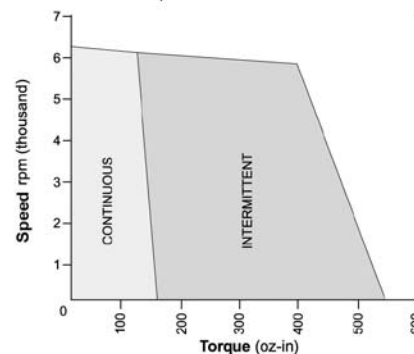
BN42-23AF-01: Continuous & Intermittent Operation at 24 Volt DC



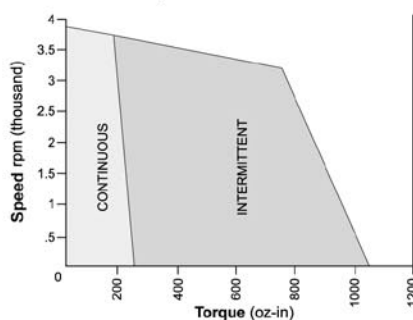
BN42-23AF-02: Continuous & Intermittent Operation at 50 Volt DC



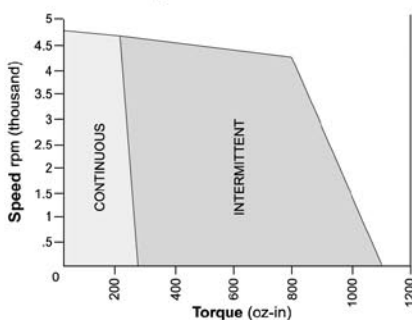
BN42-23AF-03: Continuous & Intermittent Operation at 100 Volt DC



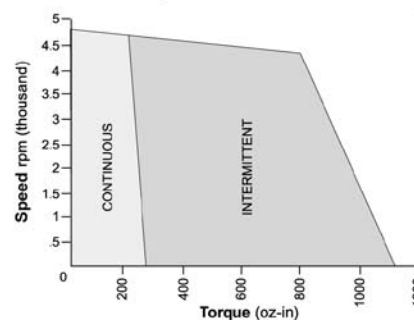
BN42-33AF-01: Continuous & Intermittent Operation at 24 Volt DC



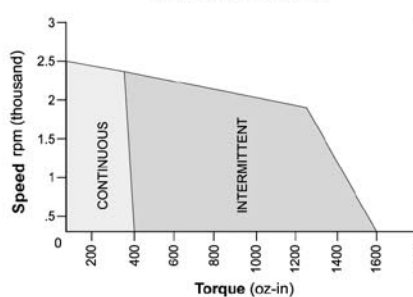
BN42-33AF-02: Continuous & Intermittent Operation at 50 Volt DC



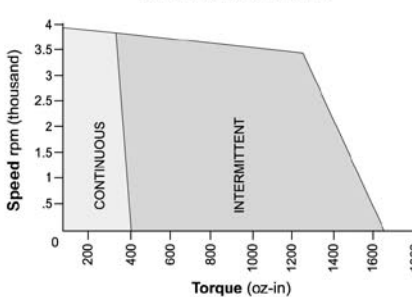
BN42-33AF-03: Continuous & Intermittent Operation at 100 Volt DC



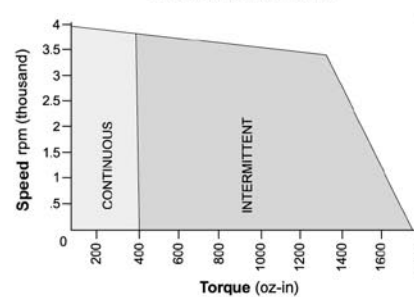
BN42-43AF-01: Continuous & Intermittent Operation at 24 Volt DC



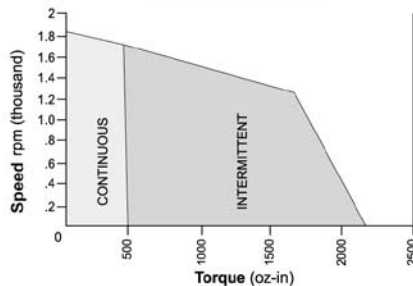
BN42-43AF-02: Continuous & Intermittent Operation at 50 Volt DC



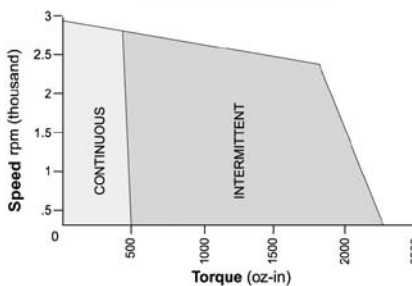
BN42-43AF-03: Continuous & Intermittent Operation at 100 Volt DC



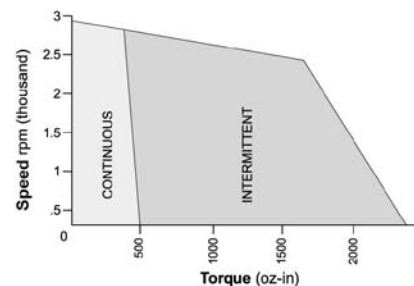
BN42-53AF-01: Continuous & Intermittent Operation at 24 Volt DC



BN42-53AF-02: Continuous & Intermittent Operation at 50 Volt DC



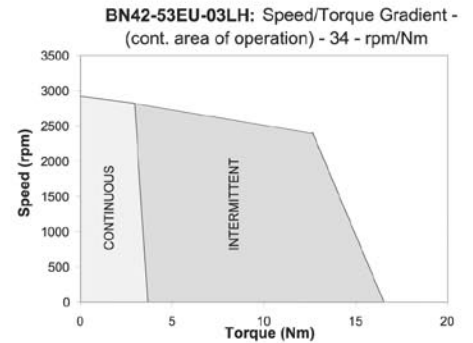
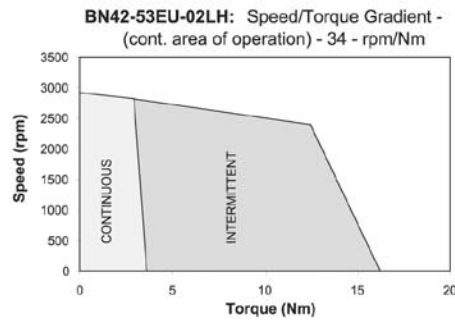
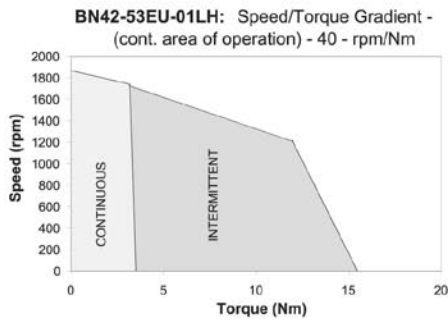
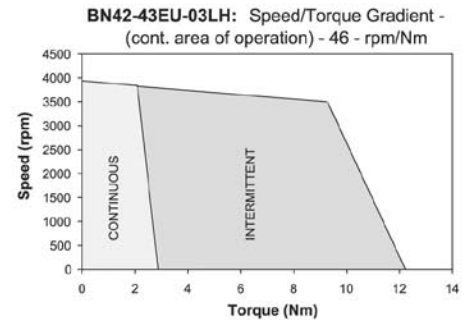
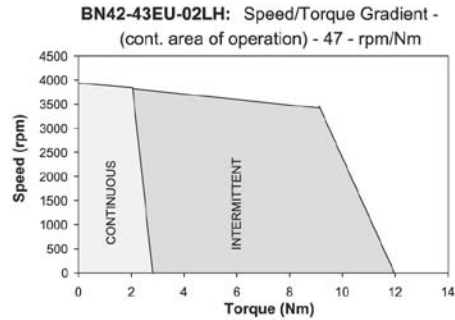
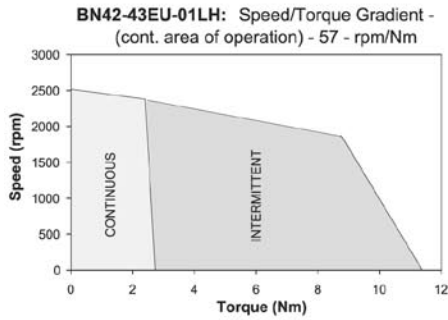
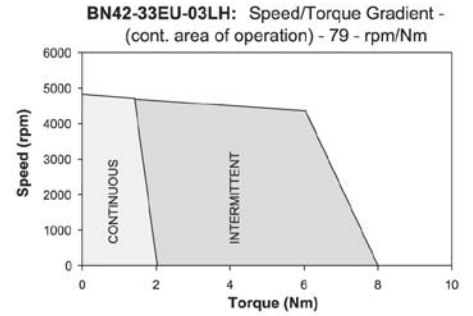
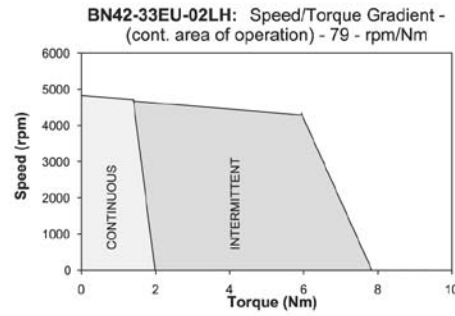
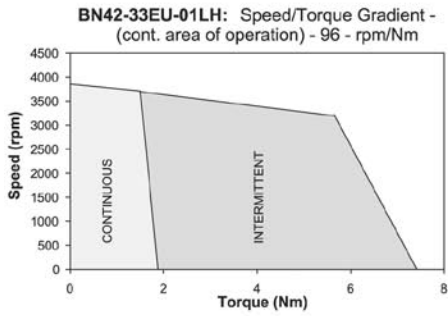
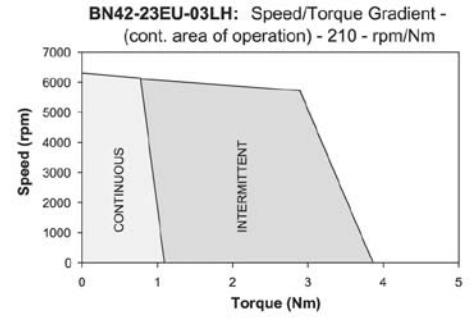
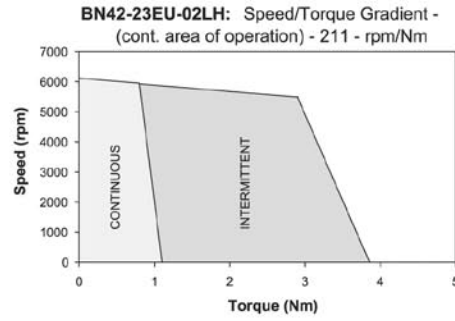
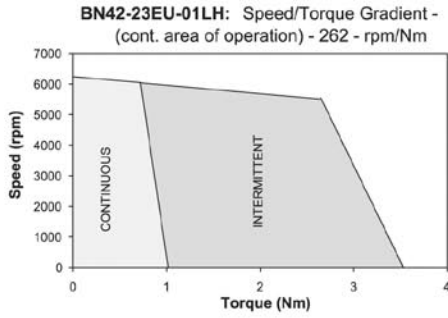
BN42-53AF-03: Continuous & Intermittent Operation at 100 Volt DC



Note: Intermittent operation is based on a 20% duty cycle of one minute on, four minutes off.
Please contact the factory regarding the duty cycle of your application.

Brushless Motors

BN42 EU Performance Curves



Note: Intermittent operation is based on a 20% duty cycle of one minute on, four minutes off.
Please contact the factory regarding the duty cycle of your application.